# Generalized characteristics for finite entropy solutions of Burgers' equation 

Andres A. Contreras Hip ${ }^{\text {a }}$, Xavier Lamy ${ }^{\text {b }}$, Elio Marconi ${ }^{\text {c,* }}$<br>${ }^{\text {a }}$ Department of Mathematics, The University of Chicago, Chicago, IL, USA<br>${ }^{\mathrm{b}}$ Institut de Mathématiques de Toulouse, UMR 5219, Université de Toulouse, CNRS, UPS<br>IMT, F-31062 Toulouse Cedex 9, France<br>${ }^{\text {c }}$ EPFL B, Station 8, CH-1015, Lausanne, Switzerland

## A R T I C L E I N F O

## Article history:

Received 16 September 2021
Accepted 24 January 2022
Communicated by Alexis Vasseur

## MSC:

35L60

## Keywords:

Generalized characteristics
Finite entropy solutions
Burgers' equation
Lagrangian representation
$L^{2}$ stability of shocks

## A B S T R A C T

We prove the existence of generalized characteristics for weak, not necessarily entropic, solutions of Burgers' equation

$$
\partial_{t} u+\partial_{x} \frac{u^{2}}{2}=0
$$

whose entropy productions are signed measures. Such solutions arise in connection with large deviation principles for the hydrodynamic limit of interacting particle systems. The present work allows to remove a technical trace assumption in a recent result by the two first authors about the $L^{2}$ stability of entropic shocks among such non-entropic solutions. The proof relies on the Lagrangian representation of a solution's hypograph, recently constructed by the third author. In particular, we prove a decomposition formula for the entropy flux across a given hypersurface, which is valid for general multidimensional scalar conservation laws.
© 2022 The Author(s). Published by Elsevier Ltd. This is an open access article under the CC BY license (http://creativecommons.org/licenses/by/4.0/).

## 1. Introduction

We consider bounded weak (not necessarily entropy) solutions of Burgers' equation

$$
\partial_{t} u+\partial_{x} \frac{u^{2}}{2}=0,
$$

or more generally a scalar conservation law

$$
\begin{equation*}
\partial_{t} u+\partial_{x} f(u)=0, \quad t>0, x \in \mathbb{R} \tag{1.1}
\end{equation*}
$$

with strictly convex flux $f \in C^{2}(\mathbb{R})$. For any entropy-flux pair $(\eta, q)$ i.e. $\eta^{\prime \prime} \geq 0$ and $q^{\prime}=\eta^{\prime} f^{\prime}$, the corresponding entropy production of a bounded weak solution $u$ is the distribution

$$
\begin{equation*}
\mu_{\eta}=\partial_{t} \eta(u)+\partial_{x} q(u) \tag{1.2}
\end{equation*}
$$

[^0]Entropy solutions are weak solutions whose entropy production is nonpositive, i.e. $\mu_{\eta} \leq 0$ for all convex entropies $\eta$, and given any bounded initial condition $u_{0}(x)$ there exists a unique entropy solution [11].

Here in contrast we consider weak solutions whose entropy productions do not necessarily have a sign: we call finite-entropy solution any bounded weak solutions of (1.1) such that

$$
\begin{equation*}
\mu_{\eta} \text { is a Radon measure for all convex } \eta \text {, } \tag{1.3}
\end{equation*}
$$

where $\mu_{\eta}$ is the entropy production defined in (1.2). This larger class of solutions is relevant in the study of large deviation principles for the hydrodynamic limit of asymmetric interacting particle systems [7,18], or for scalar conservation laws with appropriately small random forcing [2,17]. Known tools fail at completing the large deviation analysis because finite-entropy solutions do not in general have bounded variation $(B V)$. Similar issues arise in the study of the so-called Aviles-Giga energy (see [12, Introduction] for more details). In the past years, several works have proved $B V$-like structural properties for finite-entropy solutions [6,13,15,16] but the large deviation principle still seems out of reach.

A key progress would be to obtain good estimates on the distance to entropy solutions in terms of the positive part of the entropy production. Inspired by [9], the two first authors recently proposed a relative entropy approach to that question [4], but they had to assume the existence of generalized characteristics: Lipschitz curves $x(t)$ such that $x^{\prime}(t)=f^{\prime}\left(u^{ \pm}(t, x(t))\right)$ for a.e. $t$ at which $u^{+}(t, x(t))=u^{-}(t, x(t))$, where $u^{ \pm}(t, x(t))$ are the left and right traces of $u$ along $(t, x(t))$. It is well-known that $B V$ solutions admit generalized characteristics starting at any value $x(0)=x_{0}[5, \S 10.2]$, but the argument uses a stronger notion of traces than the one available for finite-entropy solutions (see the discussion in the introduction of [4]). Existence of generalized characteristics is also crucial in several recent works using relative entropy methods for hyperbolic systems of conservation laws (see e.g. [3,8,10]).

Our main result Theorem 1.1 establishes the existence of generalized characteristics for finite-entropy solutions. As a corollary, the results in [4] are valid for any finite-entropy solution of Burgers' equation.

Theorem 1.1. Let $u:[0, T] \times \mathbb{R} \rightarrow \mathbb{R}$ be a finite-entropy weak solution of (1.1) with strictly convex flux $f \in C^{2}(\mathbb{R})$. For any $x_{0} \in \mathbb{R}$, there exists a generalized characteristic of $u$ starting at $x_{0}$, that is, a Lipschitz curve $x:\left[t_{0}, T\right] \rightarrow \mathbb{R}$ such that $x(0)=x_{0}$ and

$$
x^{\prime}(t)=f^{\prime}\left(u^{ \pm}(t, x(t))\right) \quad \text { for a.e. } t \in[0, T] \text { s.t. } u^{+}(t, x(t))=u^{-}(t, x(t)),
$$

where $u^{ \pm}(t, x(t))$ denote the left and right traces of $u$ along $(t, x(t))$.
Remark 1.2. Finite-entropy solutions have traces which are reached strongly in $L^{1}$ :

$$
\underset{y \rightarrow 0^{+}}{\operatorname{ess}} \lim _{0}^{T}\left|u(t, x(t) \pm y)-u^{ \pm}(t, x(t))\right| d t=0 .
$$

This is proved in [19] for entropy solutions, but the proof uses only a kinetic formulation which is also valid for finite-entropy solutions [6]. In particular, for a.e. $t \in[0, T]$ such that $u^{+}(t, x(t)) \neq u^{-}(t, x(t))$ we have the Rankine-Hugoniot condition

$$
x^{\prime}(t)=\frac{f\left(u^{+}(t, x(t))\right)-f\left(u^{-}(t, x(t))\right)}{u^{+}(t, x(t))-u^{-}(t, x(t))} .
$$

The strategy of proof relies on the Lagrangian representation recently introduced by the third author [15, 16], building on the kinetic formulation [14]. A central ingredient is valid for general multidimensional scalar conservation laws and is of independent interest: in Theorem 1.4 we obtain a formula for the entropy flux
across a hypersurface in terms of the Lagrangian representation. In order to state this result, we consider finite-entropy solutions of

$$
\begin{equation*}
\partial_{t} u+\nabla_{x} \cdot f(u)=0, \quad t \in(0, T), x \in \mathbb{R}^{d} \tag{1.4}
\end{equation*}
$$

where the flux $f$ is now any $C^{2}$ function $f: \mathbb{R} \rightarrow \mathbb{R}^{d}$, and the finite-entropy condition amounts to

$$
\mu_{\eta}:=\partial_{t} \eta(u)+\nabla_{x} \cdot q(u) \quad \text { is a Radon measure for all convex } \eta,
$$

and associated entropy flux $q$ given by $q^{\prime}=\eta^{\prime} f^{\prime}$. In [16] the third author proves the existence of a Lagrangian representation of the hypograph of $u$, that is, a nonnegative finite measure $\omega_{h}$ on the set of curves

$$
\Gamma=\left\{\gamma=\left(\gamma_{x}, \gamma_{v}\right) \in B V([0, T]) ; \mathbb{R}^{d} \times[0,1]: \gamma_{x} \text { is Lipschitz }\right\}
$$

with the following three properties.

- For all $t \in[0, T)$, the pushforward $\left(e_{t}\right) \sharp \omega_{h}$ by the evaluation map $e_{t}: \gamma \mapsto \gamma\left(t^{+}\right)$is uniform on the hypograph of $u(t)$,

$$
\begin{equation*}
\left(e_{t}\right) \sharp \omega_{h}=\mathcal{L}^{d+1}\left\lfloor\left\{(x, v) \in \mathbb{R}^{d} \times[0,1]: v<u(t, x)\right\} .\right. \tag{1.5}
\end{equation*}
$$

- The measure $\omega_{h}$ is concentrated on curves $\gamma \in \Gamma$ satisfying the characteristic differential equation

$$
\begin{equation*}
\gamma_{x}^{\prime}(t)=f^{\prime}\left(\gamma_{v}(t)\right) \quad \text { for a.e. } t \in[0, T) . \tag{1.6}
\end{equation*}
$$

In particular $\gamma_{x}$ is $S$-Lipschitz for $\omega_{h}$-a.e. $\gamma$, where $S=\sup \left|f^{\prime}\right|([0,1])$ is the maximal speed.

- The total variation of $\gamma_{v}$ is controlled by

$$
\begin{equation*}
\int_{\Gamma} \operatorname{TotVar} \gamma_{v} d \omega_{h}<\infty \tag{1.7}
\end{equation*}
$$

Remark 1.3. One can also define a Lagrangian representation $\omega_{e}$ of the epigraph of $u$. This representation satisfies the same properties as the representation of the hypograph, where (1.5) is replaced by

$$
\left(e_{t}\right) \sharp \omega_{e}=\mathcal{L}^{d+1}\left\lfloor\left\{(x, v) \in \mathbb{R}^{d} \times[0,1]: v>u(t, x)\right\} .\right.
$$

We will sometimes loosely refer to typical curves chosen according to the measure $\omega_{h}$ (respectively $\omega_{e}$ ), as curves of the hypograph (respectively epigraph).

Our second main result is a decomposition formula for the entropy flux across a given hypersurface, along the curves of the Lagrangian representation.

Theorem 1.4. Let u be a finite-entropy solution of (1.4) with Lagrangian representation $\omega_{h}$ of its hypograph. Let $\Sigma \subset(0, T) \times \mathbb{R}^{d}$ be a Lipschitz hypersurface. Then $\omega_{h}$-almost every curve $\gamma \in \Gamma$ intersects $\Sigma$ at most a finite number of times, in the sense that

$$
\left\{t \in(0, T):\left(t, \gamma_{x}(t)\right) \in \Sigma\right\} \quad \text { is finite. }
$$

For any open set $U \subset(0, T) \times \mathbb{R}^{d}$ such that $U \backslash \Sigma$ has two connected components $\Sigma^{ \pm}$, denote by $\nu$ the unit normal vector to $\Sigma$ pointing from $\Sigma^{-}$to $\Sigma^{+}$and by $u^{ \pm}$the traces of $u$ on the corresponding sides. Then, for any entropy-entropy flux pair $(\eta, q)$ with

$$
\eta(0)=0, \quad q(0)=0,
$$

the entropy flux across $\Sigma$ from $\Sigma^{-}$satisfies

$$
\int_{\Sigma} \nu \cdot\left(\eta\left(u^{-}\right), q\left(u^{-}\right)\right) \Phi d \mathcal{H}^{d}=\int_{\Gamma}\left\langle F_{\gamma}^{-}, \eta \otimes \Phi\right\rangle d \omega_{h}(\gamma) \quad \text { for all } \Phi \in C_{c}^{\infty}(U)
$$

where

$$
\begin{align*}
\left\langle F_{\gamma}^{-}, \eta \otimes \Phi\right\rangle= & \sum_{t \in I_{\gamma}^{+}} \eta^{\prime}\left(\gamma_{v}\left(t^{-}\right)\right) \Phi\left(t, \gamma_{x}(t)\right)-\sum_{t \in I_{\gamma}^{-}} \eta^{\prime}\left(\gamma_{v}\left(t^{+}\right)\right) \Phi\left(t, \gamma_{x}(t)\right)  \tag{1.8}\\
& +\sum_{t \in B_{\gamma}^{-}}\left(\eta^{\prime}\left(\gamma_{v}\left(t^{-}\right)\right)-\eta^{\prime}\left(\gamma_{v}\left(t^{+}\right)\right)\right) \Phi\left(t, \gamma_{x}(t)\right)
\end{align*}
$$

Here $I_{\gamma}^{ \pm}$and $B_{\gamma}^{-}$are disjoint subsets of the intersection times of $\left(t, \gamma_{x}(t)\right)$ with $U \cap \Sigma, I_{\gamma}^{+}$corresponding to crossings from $\Sigma^{-}$to $\Sigma^{+}, I_{\gamma}^{-}$to crossings from $\Sigma^{+}$to $\Sigma^{-}$, and $B_{\gamma}^{-}$to bounces on $\Sigma$ from $\Sigma_{-}$.

Remark 1.5. Specifically, the sets $I_{\gamma}^{ \pm}, B_{\gamma}^{-}$appearing in Theorem 1.4 are given by

$$
\begin{aligned}
& I_{\gamma}^{+}=\left\{t \in(0, T):\left(t, \gamma_{x}(t)\right) \in U \cap \Sigma,\left(t \pm \delta, \gamma_{x}(t \pm \delta)\right) \in \Sigma^{ \pm} \text {for } 0<\delta \ll 1\right\}, \\
& I_{\gamma}^{-}=\left\{t \in(0, T):\left(t, \gamma_{x}(t)\right) \in U \cap \Sigma,\left(t \pm \delta, \gamma_{x}(t \pm \delta)\right) \in \Sigma^{\mp} \text { for } 0<\delta \ll 1\right\} \\
& B_{\gamma}^{-}=\left\{t \in(0, T):\left(t, \gamma_{x}(t)\right) \in U \cap \Sigma,\left(t \pm \delta, \gamma_{x}(t \pm \delta)\right) \in \Sigma^{-} \text {for } 0<\delta \ll 1\right\}
\end{aligned}
$$

Remark 1.6. For the Lagrangian representation $\omega_{e}$ of the epigraph of $u$ (see Remark 1.3), the identity of Theorem 1.4 becomes,

$$
\int_{\Sigma}\left(\eta\left(u^{-}\right), q\left(u^{-}\right)\right) \cdot \nu \Phi(t, x) d \mathcal{H}^{d}(t, x)=-\int_{\Gamma}\left\langle F_{\gamma}^{-}, \eta \otimes \Phi\right\rangle d \omega_{e}(\gamma),
$$

provided $\eta(1)=0$ and $q(1)=0$.
Once the first assertion of Theorem 1.4 is established, that typical curves of the hypograph have finite intersection with $\Sigma$, the flux formula (1.8) follows from rather natural manipulation, using the Lagrangian property (1.5) that $\left(e_{t}\right) \sharp \omega_{h}=\mathbf{1}_{v<u(t, x)} d x d v$ in order to link values of $u$ with the Lagrangian representation. The finite intersection property is a consequence of a transverse intersection property: tangential intersections are negligible, essentially thanks to the fact that $\Sigma$ is of codimension 1 while $\left(e_{t}\right) \sharp \omega_{h}$ is absolutely continuous with respect to the Lebesgue measure.

The proof of Theorem 1.1 uses the flux formula of Theorem 1.4 and the property, established in [15], that for Burgers' Eq. (1.1) curves of the hypograph cannot cross from the left curves of the epigraph. This enables us to construct $x(t)$ as a curve that cannot be crossed from the left by any curve of the hypograph, nor from the right by curves of the epigraph. This implies, via the flux formula (1.8) from which some terms can then be dropped, inequalities on the entropy flux across $x(t)$ that can only be satisfied by a generalized characteristic.

The article is organized as follows. In Section 2 we prove Theorem 1.1 as a consequence of Theorem 1.4, whose proof is given in Section 3.

## 2. Proof of Theorem 1.1

In this section we prove Theorem 1.1, that is, the existence of characteristics for finite-entropy solutions of Burgers. Aside from the flux formula from Theorem 1.4, the main tool is the existence of a curve $x(t)$ that cannot be crossed from the left by (typical) curves of the hypograph, nor from the right by curves of the epigraph. This is the only place where we need the strict convexity of the flux $f$.

Lemma 2.1. Let $u:[0, T] \times \mathbb{R} \rightarrow[0,1]$ be a finite-entropy solution of (1.1) with strictly convex flux $f$. For any $x_{0} \in \mathbb{R}$, there exists a Lipschitz curve $x:[0, T] \rightarrow \mathbb{R}$ such that $x(0)=x_{0}$, and

$$
\begin{equation*}
\omega_{h}\left(\left\{\gamma \in \Gamma: \exists t_{1}<t_{2}, \gamma_{x}\left(t_{1}\right)<x\left(t_{1}\right), \gamma_{x}\left(t_{2}\right)>x\left(t_{2}\right)\right\}\right)=0 \tag{2.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\omega_{e}\left(\left\{\gamma \in \Gamma: \exists t_{1}<t_{2}, \gamma_{x}\left(t_{1}\right)>x\left(t_{1}\right), \gamma_{x}\left(t_{2}\right)<x\left(t_{2}\right)\right\}\right)=0 . \tag{2.2}
\end{equation*}
$$

Proof of Lemma 2.1. For any $(t, x) \in[0, T) \times \mathbb{R}$ we define a curve $\hat{\gamma}_{t, x}:[t, T] \rightarrow \mathbb{R}$ by

$$
\hat{\gamma}_{t, x}(s)=\inf \left\{y \in \mathbb{R}: \omega_{h}\left\{\gamma \in \Gamma: \gamma_{x}(t)<x, \gamma_{x}(s)>y\right\}=0\right\} .
$$

In other words, $\hat{\gamma}_{t, x}(s)$ is the right-most value of $y$ that can be attained at time $s \geq t$ by curves of the hypograph passing left from $x$ at time $t$. Note that $\hat{\gamma}_{t, x}$ is $S$-Lipschitz because $\gamma_{x}$ is $S$-Lipschitz for $\omega_{h}$-a.e. $\gamma$.

To obtain a curve that cannot be crossed from the left by any curves of the hypograph, we iterate this construction on small time intervals. For $\delta>0$ we let $t_{k}=k \delta$ and define an $S$-Lipschitz curve $x^{\delta}:[0, T] \rightarrow \mathbb{R}$ iteratively on $\left(t_{0}, t_{1}\right],\left(t_{1}, t_{2}\right]$, etc., by setting

$$
\begin{aligned}
x^{\delta}(0) & =x_{0}, \\
x^{\delta}(t) & =\hat{\gamma}_{t_{k}, x^{\delta}\left(t_{k}\right)}(t) \quad \text { for } t \in\left(t_{k}, t_{k+1}\right] \cap[0, T], \quad k \delta \leq T .
\end{aligned}
$$

For all $t \in[0, T]$, the sequence $x^{1 / 2^{n}}(t)$ is monotone, and we set

$$
x(t)=\lim _{n \rightarrow \infty} x^{1 / 2^{n}}(t)=\sup _{n>0} x^{1 / 2^{n}}(t) .
$$

From the definitions of $x^{\delta}$ and $\hat{\gamma}_{t, x}$ we have that, for any $m \geq n>0$,

$$
\omega_{h}\left(\left\{\gamma: \exists t_{1} \in 2^{-n} \mathbb{N}, t_{2}>t_{1}, \gamma_{x}\left(t_{1}\right)<x^{1 / 2^{m}}\left(t_{1}\right), \gamma_{x}\left(t_{2}\right)>x^{1 / 2^{m}}\left(t_{2}\right)\right\}\right)=0
$$

and since $x(t)=\lim x^{1 / 2^{m}}(t)$ we deduce that

$$
\omega_{h}\left(\left\{\gamma: \exists t_{1} \in \bigcup_{n>0}\left(2^{-n} \mathbb{N}\right), t_{2}>t_{1}, \gamma_{x}\left(t_{1}\right)<x\left(t_{1}\right), \gamma_{x}\left(t_{2}\right)>x\left(t_{2}\right)\right\}\right)=0
$$

Property (2.1) follows because $x$ is Lipschitz, and so is $\gamma_{x}$ for any $\gamma \in \Gamma$.
Property (2.2) is a consequence of the fact, proven in [15, Proposition 6], that curves of the epigraph cannot cross from the right curves of the hypograph, because $f$ is strictly convex. The proof in [15] deals with the case $f(u)=u^{2} / 2$, but the proof can be repeated as it is, replacing the characteristic condition $\dot{\gamma}_{x}(t)=\gamma_{v}(t)$ valid for $f(u)=u^{2} / 2$, with the more general $\dot{\gamma}_{x}(t)=f^{\prime}\left(\gamma_{v}(t)\right)$ and using that $f^{\prime}$ is increasing. Specifically, exchanging the roles of $\omega_{e}$ and $\omega_{h}$ in [15, Proposition 6], we have that $\omega_{e}$ is concentrated on a set $\Gamma_{e}$ such that, for any $\bar{\gamma} \in \Gamma_{e}$ and $t_{1}<t_{2} \in[0, T]$,

$$
\begin{equation*}
\omega_{h}\left(\left\{\gamma: \gamma_{x}\left(t_{1}\right)<\bar{\gamma}_{x}\left(t_{1}\right), \gamma_{x}\left(t_{2}\right)>\bar{\gamma}_{x}\left(t_{2}\right)\right\}\right)=0 . \tag{2.3}
\end{equation*}
$$

Assuming that $\Gamma_{e}$ has non-empty intersection with the set in (2.2) and using the definition of $x(t)$, we would obtain a curve $\bar{\gamma} \in \Gamma_{e}$ and $t_{1}<t_{2}$ such that

$$
\bar{\gamma}_{x}\left(t_{1}\right)>x^{1 / 2^{n}}\left(t_{1}\right) \quad \text { and } \quad \bar{\gamma}_{x}\left(t_{2}\right)<x^{1 / 2^{n}}\left(t_{2}\right),
$$

for some large enough $n$, and so there is $k \geq 0, t_{k}=k / 2^{n}$, and $t \in\left(t_{k}, t_{k+1}\right]$ such that

$$
\bar{\gamma}_{x}\left(t_{k}\right) \geq x^{1 / 2^{n}}\left(t_{k}\right) \quad \text { and } \quad \bar{\gamma}_{x}(t)<x^{1 / 2^{n}}(t)=\hat{\gamma}_{t_{k}, x^{1 / 2^{n}}\left(t_{k}\right)}(t)
$$

By definition of $\hat{\gamma}_{t, x}$ this implies that

$$
\omega_{h}\left(\left\{\gamma: \gamma_{x}\left(t_{k}\right)<\bar{\gamma}_{x}\left(t_{k}\right), \gamma_{x}(t)>\bar{\gamma}_{x}(t)\right\}\right)>0,
$$

thus contradicting (2.3) and concluding the proof of (2.2).

The rest of Theorem 1.1's proof consists in showing that the curve $x(t)$ provided by Lemma 2.1 is a generalized characteristic. Thanks to the property (2.1) ensuring that curves of the hypograph typically do not cross $x(t)$ from the left, in the flux formula (1.8) for the flux $F_{\gamma}^{-}$along a curve $\gamma$ across $x(t)$, there will be no contribution of the set $I_{\gamma}^{+}$(times of crossings from left to right). Moreover, at typical times $t$ where the traces $u^{ \pm}(t, x(t))$ agree, the contribution of the set $B_{\gamma}^{-}$(times of bounces from the left) will be negligible. As a consequence, for monotone entropies $\eta$ the flux across $x(t)$ will have a sign, providing a lower bound on $x^{\prime}(t)$. The matching upper bound is then obtained similarly by using the property (2.2) that curves of the hypograph typically do not cross $x(t)$ from the right.

Before proceeding to the proof of Theorem 1.1, let us be more specific about why the contribution of $B_{\gamma}^{-}$ will be negligible at points where the traces agree. This is due to the fact that entropy dissipation can be decomposed along the Lagrangian representation, and jumps in $\gamma_{v}$ create an amount of entropy dissipation that is incompatible with the absence of jump $u^{+}(t, x(t))=u^{-}(t, x(t))$. We recall here the relevant result from [16]. We denote by $\nu$ the total entropy dissipation

$$
\begin{equation*}
\nu=\bigvee_{\left|\eta^{\prime \prime}\right| \leq 1}\left|\mu_{\eta}\right|, \tag{2.4}
\end{equation*}
$$

where $\bigvee$ stands for the lowest upper bound of a family of measures (as defined e.g. in [1, Definition 1.68]). As a consequence of [16, Propositions $5.11 \& 5.12$ ] there is a Lagrangian representation $\omega_{h}$ such that

$$
\begin{equation*}
\int_{\Gamma}\left|D \gamma_{v}\right|\left(\left\{t \in A: \gamma_{x}(t) \in B\right\}\right) d \omega_{h}(\gamma)=\nu(A \times B) \tag{2.5}
\end{equation*}
$$

for any borelian sets $A \subset[0, T], B \subset \mathbb{R}$.

Remark 2.2. It is proved in [15] that for Burgers equation the measure $\nu$ is actually equal to $\left|\mu_{\eta_{0}}\right|$ for $\eta_{0}(u)=u^{2} / 2$, but we will not need it here.

Proof of Theorem 1.1. We assume without loss of generality that $u$ takes values in $[0,1]$ and show that the curve $x(t)$ from Lemma 2.1 is a generalized characteristic. As a consequence of [6], at almost every $t_{0} \in[0, T]$ such that the traces $u^{ \pm}\left(t_{0}, x\left(t_{0}\right)\right)$ are equal, we must have

$$
\begin{equation*}
\lim _{r \rightarrow 0} \frac{\nu\left(B_{r}\left(t_{0}, x_{0}\right)\right)}{r}=0 \tag{2.6}
\end{equation*}
$$

where $x_{0}=x\left(t_{0}\right)$ and $\nu$ is the total entropy dissipation (2.4). Hence we fix $t_{0}$ a Lebesgue point of $x^{\prime}$ such that $\left(t_{0}, x_{0}\right)$ is a Lebesgue point of $u^{ \pm}$satisfying (2.6), and prove that $x^{\prime}\left(t_{0}\right)=f^{\prime}\left(u_{0}\right)$, where $u_{0}=u^{+}\left(t_{0}, x\left(t_{0}\right)\right)=u^{-}\left(t_{0}, x\left(t_{0}\right)\right) \in(0,1)$.

Let $\eta$ be a nondecreasing $C^{2}$ entropy such that $\eta(0)=0$ and $q$ be the associated entropy flux with $q(0)=0$. Given a non-negative test function $\Phi$ and applying the flux formula of Theorem 1.4 to the curve $x$, we obtain

$$
\begin{aligned}
& \int_{0}^{T} q\left(u^{-}(t, x(t))\right)-x^{\prime}(t) \eta\left(u^{-}(t, x(t))\right) \Phi(t, x(t)) d t \\
& =\int_{\Gamma} \sum_{t \in I_{\gamma}^{+}} \eta^{\prime}\left(\gamma_{v}\left(t^{-}\right)\right) \Phi(t, x(t)) d \omega_{h}(\gamma)-\int_{\Gamma} \sum_{t \in I_{\gamma}^{-}} \eta^{\prime}\left(\gamma_{v}\left(t^{+}\right)\right) \Phi(t, x(t)) d \omega_{h}(\gamma) \\
& \quad+\int_{\Gamma} \sum_{t \in B_{\gamma}^{-}}\left(\eta^{\prime}\left(\gamma_{v}\left(t^{-}\right)\right)-\eta^{\prime}\left(\gamma_{v}\left(t_{+}\right)\right)\right) d \omega_{h}(\gamma) .
\end{aligned}
$$

The first term on the right-hand side is zero thanks to the property (2.1) that typical curves of the hypograph do not cross $x(t)$ from the left. The second term is nonpositive because $\eta$ is non decreasing, so we deduce

$$
\begin{align*}
& \int_{0}^{T} q\left(u^{-}(t, x(t))\right)-x^{\prime}(t) \eta\left(u^{-}(t, x(t))\right) \Phi(t, x(t)) d t  \tag{2.7}\\
& \leq \int_{\Gamma} \sum_{t \in B_{\gamma}^{-}}\left(\eta^{\prime}\left(\gamma_{v}\left(t^{-}\right)\right)-\eta^{\prime}\left(\gamma_{v}\left(t_{+}\right)\right)\right) d \omega_{h}(\gamma)
\end{align*}
$$

Next we choose

$$
\Phi(t, x)=\chi_{\delta}(t) \varphi(x), \quad \chi_{\delta}(t)=\frac{1}{\delta} \chi\left(\frac{t-t_{0}}{\delta}\right),
$$

where $\chi$ is a smooth cut-off function with $0 \leq \chi(t) \leq \mathbf{1}_{|t| \leq 1}$ and $\int \chi=1$, and $\varphi$ is any smooth compactly supported non-negative function such that $\varphi\left(x_{0}\right)=1$. Using the Lebesgue point properties of $t_{0}$ we may pass to the limit $\delta \rightarrow 0$ on the left-hand side of (2.7) and obtain

$$
\begin{aligned}
& q\left(u_{0}\right)-x^{\prime}\left(t_{0}\right) \eta\left(u_{0}\right) \\
& \leq\left\|\eta^{\prime \prime}\right\|_{\infty} \limsup _{\delta \rightarrow 0} \frac{1}{\delta} \int_{\Gamma}\left|D \gamma_{v}\right|\left(\left\{t \in\left(t_{0}-\delta, t_{0}+\delta\right): \gamma_{x}(t)=x(t)\right\}\right) d \omega_{h}(\gamma) .
\end{aligned}
$$

Since $x$ is $S$-Lipschitz and $x\left(t_{0}\right)=x_{0}$, using (2.5) to further estimate the right-hand side we infer

$$
q\left(u_{0}\right)-x^{\prime}\left(t_{0}\right) \eta\left(u_{0}\right) \leq\left\|\eta^{\prime \prime}\right\|_{\infty} \limsup _{\delta \rightarrow 0} \frac{1}{\delta} \nu\left(B_{C \delta}\left(t_{0}, x_{0}\right)\right),
$$

where $C=\sqrt{1+S^{2}}$. Recalling (2.6) we deduce

$$
q\left(u_{0}\right)-x^{\prime}\left(t_{0}\right) \eta\left(u_{0}\right) \leq 0,
$$

for any nondecreasing $C^{2}$ entropy $\eta$ with $\eta(0)=0$, and associated entropy flux $q$ with $q(0)=0$. Approximating by $C^{2}$ functions, this is valid for any nondecreasing $\eta$ with $\eta(0)=0$. Choosing

$$
\eta(x)=(x-a) 1_{x \geq a}, q(x)=(f(x)-f(a)) 1_{x \geq a}
$$

for any $a \in\left[0, u_{0}\right)$, we deduce

$$
x^{\prime}\left(t_{0}\right) \geq \frac{f\left(u_{0}\right)-f(a)}{u_{0}-a}
$$

and letting $a \rightarrow u_{0}$ this implies $x^{\prime}\left(t_{0}\right) \geq f^{\prime}\left(u_{0}\right)$.
Using curves of the epigraph (see Remark 1.6) and the property (2.2) that typical curves of the epigraph cannot cross $x(t)$ from the right, we similarly obtain that

$$
q\left(u_{0}\right)-x^{\prime}\left(t_{0}\right) \eta\left(u_{0}\right) \geq 0
$$

for all nonincreasing entropy $\eta$ with $\eta(1)=0$, and associated entropy flux $q$ with $q(1)=0$, and applying this to

$$
\eta=(a-x) 1_{x \leq a}, q(x)=(f(a)-f(x)) 1_{x \leq a},
$$

for any $a \in\left(u_{0}, 1\right]$ we deduce the opposite inequality $x^{\prime}\left(t_{0}\right) \leq f^{\prime}\left(u_{0}\right)$.

## 3. Proof of the flux formula

In this section we prove Theorem 1.4. As in its statement, we fix $u$ a finite-entropy solution of (1.4) with Lagrangian representation $\omega_{h}$ of its hypograph, $\Sigma \subset(0, T) \times \mathbb{R}^{d}$ a Lipschitz hypersurface, and an open set $U \subset(0, T) \times \mathbb{R}^{d}$ such that $U \backslash \Sigma$ has two connected components $\Sigma^{ \pm}$. We denote by $\nu$ the unit normal vector to $\Sigma$ pointing from $\Sigma^{-}$to $\Sigma^{+}$and by $u^{ \pm}$the traces of $u$ on the corresponding sides.

We start by establishing a first decomposition formula for the flux, where the flux along a curve $\gamma$ is not yet in the geometrically meaningful form of $F_{\gamma}^{-}$in Theorem 1.4.

Lemma 3.1. For any entropy-entropy flux pair $(\eta, q)$ with $\eta(0)=0, q(0)=0$ we have

$$
\begin{equation*}
\int_{\Sigma}\left(\eta\left(u^{-}\right), q\left(u^{-}\right)\right) \cdot \nu \Phi(t, x) d \mathcal{H}^{d}(t, x)=\int_{\Gamma}\left\langle\widetilde{F}_{\gamma}, \eta \otimes \Phi\right\rangle d \omega_{h}(\gamma) \quad \forall \Phi \in C_{c}^{\infty}(U) \tag{3.1}
\end{equation*}
$$

where

$$
\begin{aligned}
\left\langle\widetilde{F}_{\gamma}, \eta \otimes \Phi\right\rangle= & -\int_{0}^{T} \mathbf{1}_{\left(t, \gamma_{x}(t)\right) \in \overline{\Sigma^{+}}} \Phi\left(t, \gamma_{x}(t)\right) D\left(\eta^{\prime} \circ \gamma_{v}\right)(d t) \\
& -\int_{0}^{T} \mathbf{1}_{\left(t, \gamma_{x}(t)\right) \in \overline{\Sigma^{+}}} \eta^{\prime}\left(\gamma_{v}(t)\right)\left(\partial_{t} \Phi+f^{\prime}\left(\gamma_{v}(t)\right) \cdot \nabla_{x} \Phi\right)\left(t, \gamma_{x}(t)\right) d t
\end{aligned}
$$

Proof. For small enough $\delta>0$ we may find a $C / \delta$-Lipschitz function $G_{\delta}: U \rightarrow[0,1]$, with $C>0$ independent of $\delta$, such that

$$
\begin{aligned}
& \quad G_{\delta}=1 \text { on } \Sigma^{+}, \quad G_{\delta}=0 \text { on }\left\{(t, x) \in \Sigma^{-}: \operatorname{dist}\left((t, x), \Sigma^{+}\right) \geq \delta\right\} \\
& \text { and } \nabla G_{\delta} \rightarrow \nu \otimes \mathcal{H}_{\lfloor\Sigma \cap U}^{d} \text { as } \delta \rightarrow 0
\end{aligned}
$$

Then we have

$$
\begin{aligned}
& \int_{\Sigma}\left(\eta\left(u^{-}\right), q\left(u^{-}\right)\right) \cdot \nu \Phi(t, x) d \mathcal{H}^{d}(t, x) \\
& =\lim _{\delta \rightarrow 0} \int(\eta(u), q(u)) \cdot \nabla G_{\delta}(t, x) \Phi(t, x) d t d x
\end{aligned}
$$

Since $\eta(0)=0$ and $q(0)=0$ we may write $\eta(u)=\int \mathbf{1}_{v<u} \eta^{\prime}(v) d v$ and $q(u)=\int \mathbf{1}_{v<u} \eta^{\prime}(v) f^{\prime}(v) d v$. Combining this with property (1.5) of the Lagrangian representation, $\left(e_{t}\right) \sharp \omega_{h}=\mathbf{1}_{v<u(t, x)} d x d v$, we find

$$
\begin{aligned}
& \int(\eta(u), q(u)) \cdot \nabla G_{\delta}(t, x) \Phi(t, x) d t d x \\
& =\int_{0}^{T}\left(1, f^{\prime}\left(\gamma_{v}(t)\right)\right) \cdot \nabla G_{\delta}\left(t, \gamma_{x}(t)\right) \eta^{\prime}\left(\gamma_{v}(t)\right) \Phi\left(t, \gamma_{x}(t)\right) d t d \omega_{h}(\gamma) \\
& =\int_{\Gamma} \int_{0}^{T} \frac{d}{d t}\left[G_{\delta}\left(t, \gamma_{x}(t)\right)\right] \eta^{\prime}\left(\gamma_{v}(t)\right) \Phi\left(t, \gamma_{x}(t)\right) d t d \omega_{h}(\gamma) \\
& =-\int_{\Gamma}\left[\int_{0}^{T} G_{\delta}\left(t, \gamma_{x}(t)\right) \Phi\left(t, \gamma_{x}(t)\right) D\left(\eta^{\prime} \circ \gamma_{v}\right)(d t)\right. \\
& \left.\quad \quad+\int_{0}^{T} G_{\delta}\left(t, \gamma_{x}(t)\right) \eta^{\prime}\left(\gamma_{v}(t)\right)\left(\partial_{t} \Phi+f^{\prime}\left(\gamma_{v}(t)\right) \cdot \nabla_{x} \Phi\right)\left(t, \gamma_{x}(t)\right) d t\right] d \omega_{h}(\gamma)
\end{aligned}
$$

For the second equality we used the fact that $\omega_{h}$ is concentrated on curves satisfying the characteristic Eq. (1.6). Note that $G_{\delta}(t, x) \rightarrow \mathbf{1}_{(t, x) \in \overline{\Sigma^{+}}}$for all $(t, x) \in U$ as $\delta \rightarrow 0$, and that the Lagrangian representation satisfies $\int_{\Gamma}(1+\operatorname{TotVar}) \gamma_{v} d \omega_{h}(\gamma)<\infty(1.7)$. Hence by dominated convergence we deduce

$$
\lim _{\delta \rightarrow 0} \int(\eta(u), q(u)) \cdot \nabla G_{\delta}(t, x) \Phi(t, x) d t d x=\int_{\Gamma}\left\langle\widetilde{F}_{\gamma}, \eta \otimes \Phi\right\rangle d \omega_{h}(\gamma)
$$

which concludes the proof of (3.1).

Next we check that $\widetilde{F}_{\gamma}=F_{\gamma}^{-}$provided $\gamma$ intersects $\Sigma$ at most a finite number of times.
Lemma 3.2. If $\gamma \in \Gamma$ intersects $\Sigma$ at most a finite number of times, that is,

$$
N_{\Sigma}(\gamma)=\operatorname{card}\left\{t \in(0, T):\left(t, \gamma_{x}(t)\right) \in \Sigma\right\}<\infty
$$

then

$$
\left\langle\widetilde{F}_{\gamma}, \eta \otimes \Phi\right\rangle=\left\langle F_{\gamma}, \eta \otimes \Phi\right\rangle \quad \forall \eta \in C^{1}(\mathbb{R}), \Phi \in C_{c}^{\infty}(U)
$$

where $\widetilde{F}_{\gamma}$ and $F_{\gamma}^{-}$are defined in Lemma 3.1 and Theorem 1.4.
Proof. Setting

$$
\begin{equation*}
\theta(t)=\mathbf{1}_{\left(t, \gamma_{x}(t)\right) \in \overline{\Sigma^{+}}}, \quad \psi(t)=\eta^{\prime}\left(\gamma_{v}(t)\right) \Phi\left(t, \gamma_{x}(t)\right) \tag{3.2}
\end{equation*}
$$

we rewrite $\widetilde{F}_{\gamma}$ as

$$
\begin{equation*}
\left\langle\tilde{F}_{\gamma}, \eta \otimes \Phi\right\rangle=-\int_{0}^{T} \theta(t) D \psi(d t) \tag{3.3}
\end{equation*}
$$

Since $\gamma$ has a finite number of intersections with $\Sigma$, we know that the $\{0,1\}$-valued function $\theta$ is $B V$. Its jump set can be decomposed as

$$
J_{\theta}=I_{\gamma}^{+} \cup I_{\gamma}^{-}
$$

where $I_{\gamma}^{ \pm}$are as in Theorem 1.4 the sets of intersection times where $\gamma$ crosses $\Sigma$ from $\Sigma^{\mp}$ to $\Sigma^{ \pm}$. They correspond to positive and negative jumps of $\theta$. Note that $\theta(t)=1$ for all $t \in J_{\theta}$. Moreover, the set $B_{\gamma}^{-}$ of intersection times where $\gamma$ bounces on $\Sigma$ from $\Sigma^{-}$corresponds to the non-jump points of $\theta$ at which its pointwise value is different from its left and right limits: for $t \in B_{\gamma}^{-}$we have $\theta\left(t^{+}\right)=\theta\left(t^{-}\right)=0$ but $\theta(t)=1$.

The function $\psi$ is also $B V$, and its jump set is included in $J_{\gamma}$, the jump set of $\gamma$. Given $v:(0, T) \rightarrow \mathbb{R}$ with bounded variation, we consider the decomposition of the measure $D v$ as in [1]: $D v=\tilde{D} v+D^{j} v$, where we denote by $\tilde{D} v$ the sum of the absolutely continuous and Cantor parts of $D v$ and by $D^{j} v$ its atomic part. In particular

$$
\left\langle\tilde{F}_{\gamma}, \eta \otimes \Phi\right\rangle=-\int_{0}^{T} \theta(t) \tilde{D} \psi(d t)-\sum_{t \in J_{\gamma}} \theta(t)\left(\psi\left(t^{+}\right)-\psi\left(t^{-}\right)\right)
$$

Since $\tilde{D} \theta=0$, we have $D(\theta \psi)=D^{j}(\theta \psi)+\tilde{D}(\theta \psi)=D^{j}(\theta \psi)+\theta \tilde{D} \psi$. Moreover $\psi$ vanishes at the boundary of $(0, T)$, therefore, integrating by parts, we get

$$
\left\langle\tilde{F}_{\gamma}, \eta \otimes \Phi\right\rangle=\sum_{t \in J_{\theta} \cup J_{\gamma}}\left(\theta\left(t^{+}\right) \psi\left(t^{+}\right)-\theta\left(t^{-}\right) \psi\left(t^{-}\right)\right)-\sum_{t \in J_{\gamma}} \theta(t)\left(\psi\left(t^{+}\right)-\psi\left(t^{-}\right)\right)
$$

Splitting the first sum for $t \in J_{\theta} \cup J_{\gamma}=\left(J_{\theta} \backslash J_{\gamma}\right) \cup\left(J_{\theta} \cap J_{\gamma}\right) \cup\left(J_{\gamma} \backslash J_{\theta}\right)$ and the second sum for $t \in J_{\gamma}=\left(J_{\gamma} \cap J_{\theta}\right) \cup\left(J_{\gamma} \backslash\left(J_{\theta} \cup B_{\gamma}^{-}\right)\right) \cup\left(J_{\gamma} \cap B_{\gamma}^{-}\right)$, and rearranging the terms we get

$$
\begin{aligned}
\left\langle\tilde{F}_{\gamma}, \eta \otimes \Phi\right\rangle= & \sum_{t \in J_{\theta} \backslash J_{\gamma}} \psi(t)\left(\theta\left(t^{+}\right)-\theta\left(t^{-}\right)\right)+\sum_{t \in J_{\gamma} \cap J_{\theta}}\left(\theta\left(t^{+}\right) \psi\left(t^{+}\right)-\theta\left(t^{-}\right) \psi\left(t^{-}\right)\right) \\
& -\sum_{t \in J_{\gamma} \cap J_{\theta}}\left(\psi\left(t^{+}\right)-\psi\left(t^{-}\right)\right)-\sum_{t \in J_{\gamma} \cap B_{\gamma}^{-}}\left(\psi\left(t^{+}\right)-\psi\left(t^{-}\right)\right) \\
= & \sum_{t \in I_{\gamma}^{+}} \psi\left(t^{-}\right)-\sum_{t \in I_{\gamma}^{-}} \psi\left(t^{+}\right)+\sum_{t \in B_{\gamma}^{-}}\left(\psi\left(t^{-}\right)-\psi\left(t^{+}\right)\right)
\end{aligned}
$$

and recalling the definitions of $\theta, \psi(3.2)$ this corresponds exactly to $\left\langle F_{\gamma}, \eta \otimes \Phi\right\rangle$.
Now Theorem 1.4 follows directly from Lemmas 3.1 and 3.2, provided we show that $\omega_{h}$-a.e. $\gamma$ intersects $\Sigma$ a finite number of times:

Proposition 3.3. Let $\Sigma \subset(0, T) \times \mathbb{R}^{d}$ be a Lipschitz hypersurface. Then

$$
\omega_{h}\left(\left\{\gamma \in \Gamma: N_{\Sigma}(\gamma)=\infty\right\}\right)=0 .
$$

Proposition 3.3 follows from the following:
Lemma 3.4. Let $h:[0, T] \times \mathbb{R}^{d-1} \rightarrow \mathbb{R}$ be Lipschitz and

$$
\Sigma=\left\{(t, \hat{x}, h(t, \hat{x})):(t, \hat{x}) \in[0, T] \times \mathbb{R}^{d-1}\right\}
$$

then $N_{\Sigma}(\gamma)<\infty$ for $\omega_{h}$-a.e. $\gamma \in \Gamma$.

Proof of Proposition 3.3. First, we know that $\Sigma$ is a locally finite union of Lipschitz graphs of the form $x_{i}=h\left(\hat{x}_{i}, t\right)$ for some $i \in\{1, \ldots, d\}$, where $\hat{x}_{i}=\left(x_{1}, \ldots, x_{i-1}, x_{i+1}, \ldots, x_{d}\right)$ or of the form $t=g(x)$. Moreover for the graphs over $x$ we can assume that $|\nabla g|<1 / S$, where $S$ is the maximal speed for curves $\gamma_{x}$. Therefore, $\omega_{h}$-a.e $\gamma$ can have at most one intersection with such a graph. For the rest of the graphs, we apply Lemma 3.4 to each graph, and we conclude that $N_{\Sigma}(\gamma)$ is finite for $\omega_{h}-$ a.e. $\gamma \in \Gamma$.

We will now prove Lemma 3.4. The strategy is to rule out non-transverse intersections, but this makes sense only at points of the hypersurface which admit a tangent space. Hence we need a preliminary result allowing us to leave out the non-differentiable points:

Lemma 3.5. Let $E \subset[0, T] \times \mathbb{R}^{d}$ be such that $\mathcal{H}^{d}(E)=0$. Then

$$
\omega_{h}\left(\left\{\gamma \in \Gamma: \exists t \in[0, T] \text { such that }\left(t, \gamma_{x}(t)\right) \in E\right\}\right)=0 .
$$

Proof of Lemma 3.5. Since $\mathcal{H}^{d}(E)=0$, for any $\varepsilon>0$ there is a sequence of balls $B\left(\left(t_{i}, x_{i}\right), r_{i}\right)$ such that

$$
E \subset \cup_{i=1}^{\infty} B\left(\left(t_{i}, x_{i}\right), r_{i}\right), \quad \sum_{i=1}^{\infty} r_{i}^{d}<\varepsilon
$$

For $\omega_{h}$-a.e. $\gamma$, since $\gamma_{x}$ is $S$-Lipschitz we have the implication

$$
\left(\exists t \in[0, T],\left(t, \gamma_{x}(t)\right) \in B\left(\left(t_{i}, x_{i}\right), r_{i}\right)\right) \quad \Longrightarrow \quad \gamma_{x}\left(t_{i}\right) \in B\left(x_{i},(1+S) r_{i}\right)
$$

and using the property (1.5) that $\left(e_{t}\right) \sharp \omega_{h}=\mathbf{1}_{v<u(t, x)} d x d v$ we deduce

$$
\begin{aligned}
& \omega_{h}\left(\left\{\gamma: \exists t \in[0, T],\left(t, \gamma_{x}(t)\right) \in B\left(\left(t_{i}, x_{i}\right), r_{i}\right)\right\}\right) \\
& \leq\left(e_{t_{i}}\right) \sharp \omega_{h}\left(B\left(x_{i},(1+S) r_{i}\right) \times[0,1]\right) \leq C r_{i}^{d}
\end{aligned}
$$

for some constant $C>0$. Summing over $i$ this implies

$$
\omega_{h}\left(\left\{\gamma: \exists t \in[0, T],\left(t, \gamma_{x}(t)\right) \in E\right\}\right) \leq C \sum_{i=1}^{\infty} r_{i}^{d}<C \varepsilon
$$

and letting $\varepsilon \rightarrow 0$ conclude the proof of Lemma 3.5.
With Lemma 3.5 at hand we now prove Lemma 3.4.

Proof of Lemma 3.4. Let $R, \varepsilon>0$, and $\delta>0$. Since $\Sigma$ is Lipschitz, it has a tangent plane at almost every point. We let $\bar{\Sigma}$ be the set of points on $\Sigma$ that have a tangent plane. Then by Lemma 3.5, we see that

$$
\begin{equation*}
\omega_{h}(\tilde{\Gamma})=0, \quad \text { where } \quad \tilde{\Gamma}:=\left\{\gamma \in \Gamma: \exists t \in[0, T], \text { s.t. }\left(t, \gamma_{x}(t)\right) \in \Sigma \backslash \bar{\Sigma}\right\} \tag{3.4}
\end{equation*}
$$

so we only need to show that $N_{\bar{\Sigma}}(\gamma)<\infty$ for $\omega_{h}$-a.e. $\gamma$. We obtain this by proving that for $\omega_{h}$-a.e. $\gamma \in \Gamma \backslash \tilde{\Gamma}$, all intersections with $\bar{\Sigma}$ must be transverse, i.e.

$$
\begin{align*}
& \omega_{h}\left(X^{-}\right)=\omega_{h}\left(X^{+}\right)=0, \quad \text { where }  \tag{3.5}\\
& X^{-}=\left\{\gamma: \exists t_{0} \in(0, T],\left(t_{0}, \gamma_{x}\left(t_{0}\right)\right) \in \bar{\Sigma},\left(1, \gamma_{x}^{\prime}\left(t_{0}^{-}\right)\right) \in T_{\left(t_{0}, \gamma_{x}\left(t_{0}\right)\right)} \Sigma\right\}, \\
& X^{+}=\left\{\gamma: \exists t_{0} \in[0, T),\left(t_{0}, \gamma_{x}\left(t_{0}\right)\right) \in \bar{\Sigma},\left(1, \gamma_{x}^{\prime}\left(t_{0}^{+}\right)\right) \in T_{\left(t_{0}, \gamma_{x}\left(t_{0}\right)\right)} \Sigma\right\} .
\end{align*}
$$

If $\gamma \in \Gamma$ is such that $N_{\bar{\Sigma}}(\gamma)=\infty$, then at an accumulation point $t \in[0, T]$ of its intersection times with $\bar{\Sigma}$, we must have either $(t, \gamma(t)) \in \Sigma \backslash \bar{\Sigma}$, or the intersection is tangential. So we have

$$
\left\{\gamma \in \Gamma: N_{\bar{\Sigma}}(\gamma)=\infty\right\} \subset \tilde{\Gamma} \cup X^{-} \cup X^{+}
$$

and then we deduce from (3.4) and (3.5) that $N_{\bar{\Sigma}}(\gamma)<\infty$ for $\omega_{h}$-a.e. $\gamma \in \Gamma$.
It remains to prove (3.5). We will prove only $\omega_{h}\left(X^{-}\right)=0$, the argument for $X^{+}$being analogous. First, we remark that the set $X^{-}$satisfies

$$
\begin{align*}
& X^{-} \subset \bigcup_{R>0} \bigcap_{\varepsilon>0} \bigcup_{\delta>0} X_{R, \varepsilon}^{\delta}, \quad \text { where }  \tag{3.6}\\
& X_{R, \varepsilon}^{\delta}=\left\{\gamma \in \Gamma:\left|\gamma_{x}(0)\right| \leq R \text { and } \exists t_{0} \in[0, T],\left(t_{0}, \gamma_{x}\left(t_{0}\right)\right) \in \bar{\Sigma},\right. \\
& \\
& \\
& \left.\quad \operatorname{dist}\left(\left(t, \gamma_{x}(t)\right), \Sigma \cap\left(\{t\} \times B_{R+S T}\right)\right) \leq \varepsilon\left(t_{0}-t\right) \forall t \in\left(t_{0}-\delta, t_{0}\right)\right\} .
\end{align*}
$$

This follows directly from the definitions of $\gamma_{x}^{\prime}$ and $T \Sigma$. Let indeed $\gamma \in X^{-}$. There obviously is an $R>0$ such that $\left|\gamma_{x}(0)\right|<R$, and then $\gamma_{x}(t) \in B_{R+S T}$ for all $t$ since $\left|\gamma_{x}^{\prime}\right| \leq S$. Suppose that $\gamma$ intersects $\bar{\Sigma}$ tangentially at time $t_{0}$, that is, $\gamma_{x}\left(t_{0}\right)=x_{0}=\left(\hat{x}_{0}, h\left(t_{0}, \hat{x}_{0}\right)\right)$, where $\hat{x}_{0} \in \mathbb{R}^{d-1}$ denotes the first $(d-1)$ components of $x_{0}$, and

$$
\gamma_{x}^{\prime}\left(t_{0}^{-}\right)=\left(\hat{y}_{0}, \nabla h\left(t_{0}, \hat{x}_{0}\right) \cdot\left(1, \hat{y}_{0}\right)\right) \quad \text { for some } \hat{y}_{0} \in \mathbb{R}^{d-1} .
$$

Let $\varepsilon>0$. By definition of $\gamma_{x}^{\prime}\left(t_{0}^{-}\right)$and $\nabla h\left(t_{0}, x_{0}\right)$, there exists $\delta>0$ such that, for all $s \in(-\delta, 0]$,

$$
\begin{aligned}
& \left|\gamma_{x}\left(t_{0}+s\right)-x_{0}-\left(s \hat{y}_{0}, \nabla h\left(t_{0}, \hat{x}_{0}\right) \cdot\left(s, s \hat{y}_{0}\right)\right)\right| \leq \frac{\varepsilon}{2}|s|, \\
& \left|h\left(t_{0}+s, \hat{x}_{0}+s \hat{y}_{0}\right)-h\left(t_{0}, \hat{x}_{0}\right)-\nabla h\left(t_{0}, \hat{x}_{0}\right) \cdot\left(s, s \hat{y}_{0}\right)\right| \leq \frac{\varepsilon}{2}|s|,
\end{aligned}
$$

which implies

$$
\left|\left(t_{0}+s, \gamma_{x}\left(t_{0}+s\right)\right)-\left(t_{0}+s, \hat{x}_{0}+s \hat{y}_{0}\right), h\left(\hat{x}_{0}\right)+h\left(t_{0}+s, \hat{x}_{0}+s \hat{y}_{0}\right)\right| \leq \varepsilon|s|,
$$

and therefore $\operatorname{dist}\left(\left(t, \gamma_{x}(t)\right), \Sigma \cap\left(\{t\} \times B_{R^{\prime}}\right)\right) \leq \varepsilon\left(t_{0}-t\right)$ for all $t \in\left(t_{0}-\delta, t_{0}\right]$, proving (3.6).
Next we claim that the sets $X_{R, \varepsilon}^{\delta}$ defined in (3.6) satisfy

$$
\begin{equation*}
\limsup _{\delta \rightarrow 0} \omega_{h}\left(X_{R, \varepsilon}^{\delta}\right) \leq C \varepsilon, \tag{3.7}
\end{equation*}
$$

for some constant $C>0$ depending only on $S, R, T$ and $\Sigma$. Since the union $\bigcup_{\delta} X_{R, \varepsilon}^{\delta}$ is nondecreasing, this implies via (3.6) that $\omega_{h}\left(X^{-}\right)=0$ and concludes the proof of Lemma 3.4.

Recall the definition

$$
\begin{aligned}
X_{R, \varepsilon}^{\delta}=\{\gamma \in \Gamma: & \left|\gamma_{x}(0)\right| \leq R \text { and } \exists t_{0} \in[0, T],\left(t_{0}, \gamma_{x}\left(t_{0}\right)\right) \in \bar{\Sigma} \\
& \left.\operatorname{dist}\left(\left(t, \gamma_{x}(t)\right), \Sigma \cap\left(\{t\} \times B_{R+S T}\right)\right) \leq \varepsilon\left(t_{0}-t\right) \forall t \in\left(t_{0}-\delta, t_{0}\right)\right\}
\end{aligned}
$$

and let $N:=\lfloor T / \delta\rfloor$. For any $\gamma \in X_{R, \varepsilon}^{\delta}$, there exists $k \in\{1, \ldots, N\}$ such that

$$
\operatorname{dist}\left(\left(k / N, \gamma_{x}(k / N)\right), \Sigma \cap\left(\{k / N\} \times B_{R+S T}\right)\right)<\varepsilon \delta
$$

and therefore

$$
X_{R, \varepsilon}^{\delta} \subseteq \bigcup_{k=1}^{N}\left\{\gamma \in \Gamma:\left(\frac{k}{N}, \gamma_{x}\left(\frac{k}{N}\right)\right) \in \Sigma \cap\left(\{k / N\} \times B_{R+S T}\right)+B(0, \varepsilon \delta)\right\}
$$

Using the Lagrangian property (1.5), we know that $e_{k / N} \sharp \omega_{h} \leq \mathcal{L}^{d+1}$, and thus

$$
\begin{aligned}
\omega_{h}\left(X_{R, \varepsilon}^{\delta}\right) & \leq \sum_{k=1}^{N} \mathcal{L}^{d+1}\left(\left(\Sigma \cap\left(\left\{\frac{k}{N}\right\} \times B_{R+S T}\right)+B(0, \varepsilon \delta)\right) \times[0,1]\right) \\
& =\sum_{k=1}^{N} \mathcal{L}^{d}\left(\Sigma \cap\left(\left\{\frac{k}{N}\right\} \times B_{R+S T}\right)+B(0, \varepsilon \delta)\right)
\end{aligned}
$$

Letting $L$ denote the Lipschitz constant of $h$, we have

$$
\begin{aligned}
& \Sigma \cap\left(\left\{\frac{k}{N}\right\} \times B_{R+S T}\right)+B(0, \varepsilon \delta) \\
& \subset\left\{x=\left(\hat{x}, x_{d}\right) \in B_{R+S T}:\left|x_{d}-h(k / N, \hat{x})\right| \leq(L+1) \varepsilon \delta\right\}
\end{aligned}
$$

and we deduce that

$$
\mathcal{L}^{d}\left(\Sigma \cap\left(\left\{\frac{k}{N}\right\} \times B_{R+S T}\right)+B(0, \varepsilon \delta)\right) \leq c(L+1) \varepsilon \delta(R+S T)^{d-1}
$$

for some absolute constant $c>0$. Therefore we have

$$
\omega_{h}\left(X_{R, \varepsilon}^{\delta}\right) \leq c(L+1) \varepsilon(R+S T)^{d-1} N \delta \leq c(L+1)(R+S T)^{d-1} T \varepsilon
$$

which implies (3.7).

## Acknowledgments

X.L. is partially supported by ANR project, France ANR-18-CE40-0023 and COOPINTER project, United States IEA-297303. E.M. is supported by the SNF, Switzerland Grant 182565.

## References

[1] L. Ambrosio, N. Fusco, D. Pallara, Functions of Bounded Variation and Free Discontinuity Problems, Clarendon Press, Oxford, 2000.
[2] G. Bellettini, L. Bertini, M. Mariani, M. Novaga, $\Gamma$-Entropy cost for scalar conservation laws, Arch. Ration. Mech. Anal. 195 (1) (2010) 261-309.
[3] G. Chen, S.G. Krupa, A.F. Vasseur, Uniqueness and weak-BV stability for $2 \times 2$ conservation laws. arXiv:2010.04761.
[4] A.A. Contreras Hip, X. Lamy, On the $L^{2}$ stability of shock waves for finite-entropy solutions of Burgers, J. Differential Equations 301 (2021) 236-265.
[5] C. Dafermos, Hyperbolic Conservation Laws in Continuum Physics, second ed., in: Grundlehren der Mathematischen Wissenschaften [Fundamental Principles of Mathematical Sciences], vol. 325, Springer-Verlag, Berlin, 2005.
[6] C. De Lellis, F. Otto, M. Westdickenberg, Structure of entropy solutions for multi-dimensional scalar conservation laws, Arch. Ration. Mech. Anal. 170 (2) (2003) 137-184.
[7] C. Kipnis, C. Landim, Scaling Limits of Interacting Particle Systems, in: Grundlehren der Mathematischen Wissenschaften [Fundamental Principles of Mathematical Sciences], vol. 320, Springer-Verlag, Berlin, 1999.
[8] S.G. Krupa, Criteria for the a-contraction and stability for the piecewise-smooth solutions to hyperbolic balance laws, Commun. Math. Sci. 18 (2020) 1493-1537.
[9] S.G. Krupa, A.F. Vasseur, On uniqueness of solutions to conservation laws verifying a single entropy condition, J. Hyperbolic Differ. Equ. 16 (1) (2019) 157-191.
[10] S.G. Krupa, A.F. Vasseur, Stability and uniqueness for piecewise smooth solutions to a nonlocal scalar conservation law with applications to Burgers-Hilbert equation, SIAM J. Math. Anal. 52 (3) (2020) 2491-2530.
[11] S.N. Kružkov, First order quasilinear equations with several independent variables, Mat. Sb. (N.S.) 81 (123) (1970) 228-255.
[12] X. Lamy, F. Otto, On the regularity of weak solutions to Burgers' equation with finite entropy production, Calc. Var. Partial Differential Equations 57 (4) (2018) 19, Paper (94).
[13] M. Lecumberry, Geometric Structure of Micromagnetic Walls and Shock Waves in Scalar Conservation Laws (Ph.D. thesis), Université de Nantes, 2003.
[14] P.-L. Lions, B. Perthame, E. Tadmor, A kinetic formulation of multidimensional scalar conservation laws and related equations, J. Amer. Math. Soc. 7 (1) (1994) 169-191.
[15] E. Marconi, The rectifiability of the entropy defect measure for Burgers equation. arXiv:2004.09932.
[16] E. Marconi, On the structure of weak solutions to scalar conservation laws with finite entropy production, Calc. Var. Partial Differential Equations 61 (32) (2022).
[17] M. Mariani, Large deviations principles for stochastic scalar conservation laws, Probab. Theory Related Fields 147 (3-4) (2010) 607-648.
[18] S. Varadhan, Large deviations for the asymmetric simple exclusion process, in: Stochastic Analysis on Large Scale Interacting Systems, in: Adv. Stud. Pure Math., vol. 39, Math. Soc. Japan, Tokyo, 2004, pp. 1-27.
[19] A. Vasseur, Strong traces for solutions of multidimensional scalar conservation laws, Arch. Ration. Mech. Anal. 160 (3) (2001) 181-193.


[^0]:    * Corresponding author.

    E-mail addresses: acontreraship@uchicago.edu (A.A. Contreras Hip), xlamy@math.univ-toulouse.fr (X. Lamy), elio.marconi@epfl.ch (E. Marconi).

