# A HARNACK TYPE INEQUALITY AND A MAXIMUM PRINCIPLE FOR AN ELLIPTIC-PARABOLIC AND FORWARD-BACKWARD PARABOLIC DE GIORGI CLASS 

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#### Abstract

We define a homogeneous parabolic De Giorgi class of order 2 which suits a mixed type class of evolution equations whose simplest example is $\mu(x) \frac{\partial u}{\partial t}-\Delta u=0$ where $\mu$ can be positive, null and negative. The functions belonging to this class are local bounded and satisfy a Harnack type inequality. Interesting by-products are Hölder-continuity, at least in the "evolutionary" part of $\Omega$ and in particular in the interface $I$ where $\mu$ change sign, and an interesting maximum principle.


1. Introduction. In the paper [7] (see also [6]), given $\Omega$ open subset of $\mathbf{R}^{n}$ and $T>0$, we studied some properties of mixed type equations of the type

$$
\begin{equation*}
\mu(x) \frac{\partial u}{\partial t}-\operatorname{div}(A(x, t, u, D u))=0 \quad \text { in } \Omega \times(0, T) \tag{1}
\end{equation*}
$$

where $\mu \in L_{\text {loc }}^{1}(\Omega)$ may be positive, negative and null and $A$ satisfies

$$
\begin{equation*}
\lambda(x)|\xi|^{2} \leq(A(x, t, u, \xi), \xi) \leq C \lambda(x)|\xi|^{2} \tag{2}
\end{equation*}
$$

for every $\xi \in \mathbf{R}^{n}$ and for a.e. $(x, t) \in \Omega \times(0, T)$ and $u \in \mathbf{R}$, for a given positive constant $C$.

In particular we study local solutions of (1), in fact a wider class which can contain also functions which are not solutions, a suitable De Giorgi class of functions containing the solutions of (1), showing first a local boundedness result and then a suitable Harnack inequality for that class.

As a byproduct we get Hölder-continuity for the functions belonging to that class, at least in the region where $\mu \neq 0$ (see Section 6), and so in particular in the regions where $\mu$ changes sign.

Here we give some equivalent formulations of the Harnack inequality and, as a consequence, we show that a maximum principle holds. The interesting thing is that if $\mu$ takes both the positive and the negative sign the maximum principle we get is similar to the analogous result in the elliptic case. This means that it is sufficient for a function $u$ to have an interior maximum, or minimum, point to get that $u$ is constant in the whole $\Omega \times(0, T)$.

[^0]2. Preliminaries and assumptions. We start recalling the definition of Muckenhoupt weight, where by weight we mean an almost everywhere non-negative function in $L_{\mathrm{loc}}^{1}\left(\mathbf{R}^{n}\right)$. Obviously if $\omega$ and $\omega^{-1}$ are weights then $\omega>0$ almost everywhere. Sometimes we will write
$$
\omega(A) \quad \text { instead of } \quad \int_{A} \omega(x) d x, \quad A \subset \mathbf{R}^{n}
$$

Definition 2.1. Let $p>1, K>0$ be constants, $\omega$ a weight. We say that $\omega$ belongs to the class $A_{p}(K)$ if

$$
\left(f_{B} \omega d x\right)^{1 / p}\left(f_{B} \omega^{-1 /(p-1)} d x\right)^{(p-1) / p} \leq K \quad \text { for every ball } B \subset \mathbf{R}^{n}
$$

We say that $\omega$ belongs to the class $A_{\infty}(K, \varsigma)$ if (by $\omega(B)$ we will denote the quantity $\left.\int_{B} \omega d x\right)$

$$
\frac{\omega(S)}{\omega(B)} \leq K\left(\frac{|S|}{|B|}\right)^{\varsigma}
$$

for every ball $B$ and every measurable set $S \subset B$.
We denote by $A_{p}=\bigcup_{K \geq 1} A_{p}(K)$. It turns out (see, e.g., [2]) that $A_{\infty}=\bigcup_{p>1} A_{p}$.
Another condition useful below (essentially to get the Sobolev-Poincaré inequality) is the following.

Definition 2.2. For a pair of weights $\nu, \omega$ in $\mathbf{R}^{n}$ and $p, q$ with $1<p<q, K>0$ we will write

$$
(\nu, \omega) \in B_{p, q}(K)
$$

if for every pair of balls $B_{r}(\bar{x}), B_{\rho}(\bar{x})$ with $r<\rho$ and $\bar{x} \in \mathbf{R}^{n}$

$$
\left(\frac{\left|B_{r}(\bar{x})\right|}{\left|B_{\rho}(\bar{x})\right|}\right)^{\alpha / n}\left(\frac{\nu\left(B_{r}(\bar{x})\right)}{\nu\left(B_{\rho}(\bar{x})\right)}\right)^{1 / q}\left(\frac{\omega\left(B_{r}(\bar{x})\right)}{\omega\left(B_{\rho}(\bar{x})\right)}\right)^{-1 / p} \leq K
$$

Given two weights $\nu \geq 0$ and $\omega>0$ a.e. and the quantity

$$
\|u\|_{\nu, \omega}^{2}:=\int_{\Omega} u^{2}(x) \nu(x) d x+\int_{\Omega}|D u|^{2}(x) \omega(x) d x
$$

one can define a weighted Sobolev space

$$
H^{1}(\Omega ; \nu, \omega)
$$

as the completion of

$$
\left\{u \in C^{1}(\Omega) \mid\|u\|_{\nu, \omega}<+\infty\right\}
$$

even if $\nu \geq 0$ (see [5]).
Assumptions about $\mu$ and $\lambda$. Now consider two functions $\mu$ and $\lambda$, which will be the ones appearing in (1) and (2), defined in $\mathbf{R}^{n}, \lambda$ positive almost everywhere, while $\mu$ may be positive, null and negative, we define

$$
\mu_{\lambda}:= \begin{cases}\mu & \text { if } \mu \neq 0 \\ \lambda & \text { if } \mu=0\end{cases}
$$

Once considered $\Omega$ on open subset of $\mathbf{R}^{n}$ and $T>0$ we require $\mu$ and $\lambda$ to satisfy what follows: there is $q>2$ such that

$$
\begin{aligned}
& \text { (H.1) } \quad \lambda \in A_{2}\left(K_{1}\right), \\
& \text { (H.2) } \quad\left(|\mu|_{\lambda}, \lambda\right) \in B_{2, q}^{1}\left(K_{2}\right), \\
& \text { (H.3) } \quad|\mu|_{\lambda} \in A_{\infty}\left(K_{3}, \varsigma\right) .
\end{aligned}
$$

These conditions garantee the validity of the Sobolev-Poincaré type inequality

$$
\begin{equation*}
\left[\frac{1}{|\mu|_{\lambda}\left(B_{\rho}\right)} \int_{B_{\rho}}|u(x)|^{2 \kappa}|\mu|_{\lambda}(x) d x\right]^{1 / 2 \kappa} \leq \gamma_{1} \rho\left[\frac{1}{\lambda\left(B_{\rho}\right)} \int_{B_{\rho}}|D u(x)|^{2} \lambda(x) d x\right]^{1 / 2} \tag{3}
\end{equation*}
$$

for some $\kappa \in(2, q)$ and of some consequent results. Moreover (H.1) and (H.3) (see, e.g., [6]) implies that $\lambda$ and $|\mu|_{\lambda}$ are doubling, i.e. there is a constant $\mathfrak{q}$ such that

$$
\begin{align*}
|\mu|_{\lambda}\left(B_{2 \rho}(x)\right) & \leq \mathfrak{q}|\mu|_{\lambda}\left(B_{\rho}(x)\right) \\
\lambda\left(B_{2 \rho}(x)\right) & \leq \mathfrak{q} \lambda\left(B_{\rho}(x)\right) \tag{4}
\end{align*}
$$

for every $x \in \Omega$ and $\rho>0$ for which $B_{2 \rho}(x) \subset \Omega$.
Moreover by (H.1) and (H.3) one gets that there are two constants k and $\tau$ such that

$$
\frac{\lambda(S)}{\lambda(B)} \leq \kappa\left(\frac{|\mu|_{\lambda}(S)}{|\mu|_{\lambda}(B)}\right)^{\tau}, \quad \frac{|\mu|_{\lambda}(S)}{|\mu|_{\lambda}(B)} \leq \kappa\left(\frac{\lambda(S)}{\lambda(B)}\right)^{\tau}
$$

for every measurable $S \subset B$, for every $B$ ball of $\mathbf{R}^{n}$. Finally by (H.2) garantees the existence of $\tilde{\alpha} \in(0,1), \tilde{K}_{2}>K_{2}$ and $\tilde{q} \in(2, q)$ such that

$$
(\text { H. } 2)^{\prime} \quad\left(|\mu|_{\lambda}, \lambda\right) \in B_{2, \tilde{q}}^{\tilde{\alpha}}\left(\tilde{K}_{2}\right) \subset B_{2,2}^{\tilde{\alpha}}\left(\tilde{K}_{2}\right)
$$

Geometric assumptions about the interfaces. By "interfaces" we mean the set where $\mu$ changes sign and is the set $I$ defined by

$$
\begin{equation*}
I_{+}=\partial \Omega_{+} \cap \Omega, \quad I_{-}=\partial \Omega_{-} \cap \Omega, \quad I_{0}=\partial \Omega_{0} \cap \Omega, \quad I:=I_{+} \cup I_{-} \cup I_{0} \tag{5}
\end{equation*}
$$

where
$\Omega_{+}:=\{x \in \Omega \mid \mu(x)>0\}, \quad \Omega_{-}:=\{x \in \Omega \mid \mu(x)<0\} \quad$ and $\quad \Omega_{0}:=\Omega \backslash\left(\Omega_{+} \cup \Omega_{-}\right)$
We will also suppose that $\Omega_{+}, \Omega_{-}$and $\Omega_{0} \backslash I$ are the union of a finite number of open and connected subsets of $\Omega$, i.e.

$$
\begin{equation*}
\Omega_{+}=\cup_{i=N_{+}} A_{i}^{+}, \quad \Omega_{-}=\cup_{i=N_{-}} A_{i}^{-}, \quad \Omega_{0}=\cup_{i=N_{0}} B_{i} \tag{6}
\end{equation*}
$$

Defining the non-negative function

$$
\lambda_{0}:= \begin{cases}\lambda & \text { in } \Omega_{0} \\ 0 & \text { in } \Omega \backslash \Omega_{0}\end{cases}
$$

we can split the weight $|\mu|_{\lambda}$ as the sum of three different non-negative functions as follows

$$
|\mu|_{\lambda}=|\mu|+\lambda_{0}=\mu_{+}+\mu_{-}+\lambda_{0}
$$

where for a given function $f$ we will denote

$$
f_{+} \quad \text { and } \quad f_{-}
$$

respectively the positive and the negative part of $f$.

About the three functions splitting $|\mu|_{\lambda}$ we will assume that (with the same constant $\mathfrak{q}$ as in (4))

$$
\left\lvert\, \begin{array}{ll}
\mu_{+}\left(B_{2 \rho}(x)\right) \leq \mathfrak{q} \mu_{+}\left(B_{\rho}(x)\right) & \text { for every } x \in \Omega_{+} \cup I_{+}  \tag{H.4}\\
\mu_{-}\left(B_{2 \rho}(y)\right) \leq \mathfrak{q} \mu_{-}\left(B_{\rho}(y)\right) & \text { for every } y \in \Omega_{-} \cup I_{-} \\
\lambda_{0}\left(B_{2 \rho}(z)\right) \leq \mathfrak{q} \lambda_{0}\left(B_{\rho}(z)\right) & \text { for every } z \in \Omega_{0} \cup I_{0}
\end{array}\right.
$$

(H.5) $\quad I$ is a such that $\lim _{\varepsilon \rightarrow 0^{+}}\left|I^{\varepsilon}\right|=0$,
where (H.4) holds for every $\rho>0$ for which $B_{2 \rho}(x) \subset \Omega$ and $I^{\varepsilon}$ is the open $\varepsilon$ neighbourhood of $I$ defined in by

$$
I^{\varepsilon}:=\{x \in \Omega \mid \operatorname{dist}(x, I)<\varepsilon\} .
$$

Assumption (H.4) is deeply connected to a geometric requirement about the set $I$ of interfaces since it has to hold in particular for points belonging to $I$. Moreover notice that (H.5) is weaker than the requirement that $I$ is a $\mathcal{H}^{n-1}$-rectifiable set because $I$ could be also not rectifiable. But for more details we refer to the last section, where some examples could better clarify these comments.
3. De Giorgi classes. In this section we define a suitable De Giorgi class for the equations (1). Honestly, compared with the following definition, in [7] a wider class is considered. In the following definition, which is simpler compared to the one given in [7], we consider a generic test function $\zeta$ while in [7] we consider only some particular $\zeta$ 's.

As already said, for a given function $f$ we will denote

$$
f_{+} \quad \text { and } \quad f_{-}
$$

the positive and the negative part of $f$. Writing $f_{ \pm}$we will mean or the positive either the negative part of $f$.
Definition 3.1. Consider $\Omega$ an open subset of $\mathbf{R}^{n}$ and $T>0$ and a point $x_{0}, \rho>0$, $t_{1}, t_{2} \in(0, T)$ with $t_{1}<t_{2}$ and a positive constant $\gamma$. We say that a function

$$
u \in L_{\mathrm{loc}}^{2}\left(0, T ; H_{\mathrm{loc}}^{1}(\Omega,|\mu|, \lambda)\right) \cap L_{\mathrm{loc}}^{\infty}\left((0, T) ; L_{\mathrm{loc}}^{2}\left(\Omega,|\mu|_{\lambda}\right)\right)
$$

belongs to the De Giorgi class $D G_{+}(\Omega, T, \mu, \lambda, \gamma)$ if

$$
\begin{aligned}
& \int_{B_{\rho}\left(x_{0}\right)}(u-k)_{+}^{2}\left(x, t_{2}\right) \zeta^{2}\left(x, t_{2}\right) \mu_{+}(x) d x+\int_{B_{\rho}\left(x_{0}\right)}(u-k)_{+}^{2}\left(x, t_{1}\right) \zeta^{2}\left(x, t_{1}\right) \mu_{-}(x) d x+ \\
& +\int_{t_{1}}^{t_{2}} \int_{B_{\rho}\left(x_{0}\right)}\left|D(u-k)_{+}\right|^{2} \zeta^{2} \lambda d x d t \leq \\
& \leq \gamma \int_{t_{1}}^{t_{2}} \int_{B_{\rho}\left(x_{0}\right)}(u-k)_{+}^{2}\left(|D \zeta|^{2} \lambda+\zeta \zeta_{t} \mu\right) d x d t+ \\
& +\int_{B_{\rho}\left(x_{0}\right)}(u-k)_{+}^{2}\left(x, t_{2}\right) \zeta^{2}\left(x, t_{2}\right) \mu_{-}(x) d x+ \\
& +\int_{B_{\rho}\left(x_{0}\right)}(u-k)_{+}^{2}\left(x, t_{1}\right) \zeta^{2}\left(x, t_{1}\right) \mu_{+}(x) d x
\end{aligned}
$$

for every $k \in \mathbf{R}$, every $\zeta \in \operatorname{Lip}(\Omega \times(0, T))$ such that $\zeta(\cdot, t) \in \operatorname{Lip}_{c}(\Omega)$ and for every $B_{\rho}\left(x_{0}\right) \times\left(t_{1}, t_{2}\right) \subset \Omega \times(0, T)$.

Similarly the class $D G_{-}(\Omega, T, \mu, \lambda, \gamma)$ will be defined in the same way taking into account $(u-k)_{-}$in the place of $(u-k)_{+}$.

Finally the class $D G(\Omega, T, \mu, \lambda, \gamma)$ will be defined as $D G_{+}(\Omega, T, \mu, \lambda, \gamma) \cap D G_{-}(\Omega$, $T, \mu, \lambda, \gamma)$.

A typical choice of a function $\zeta$ will be done in such a way that

$$
\begin{gather*}
0 \leq \zeta \leq 1, \quad \zeta_{t} \mu \geq 0 \\
|D \zeta|^{2} \lambda\left(B_{\rho}\left(x_{0}\right)\right) \quad \text { and } \quad \zeta \zeta_{t} \mu\left(B_{\rho}\left(x_{0}\right)\right) \quad \lesssim \frac{1}{(\rho-r)^{2}} \lambda\left(B_{\rho}\left(x_{0}\right)\right)  \tag{7}\\
t_{2}-t_{1} \sim \frac{|\mu|_{\lambda}\left(B_{\rho}\left(x_{0}\right)\right)}{\lambda\left(B_{\rho}\left(x_{0}\right)\right)} \rho^{2}
\end{gather*}
$$

where in (7) we precisely mean that $\zeta(\cdot, t) \in \operatorname{Lip}_{c}(\Omega)$ for every time $t \in(0, T)$ and for $r \in(0, \rho)$

$$
\begin{array}{cl}
0 \leq \zeta \leq 1 \quad \text { in } B_{\rho}\left(x_{0}\right) \times\left(t_{1}, t_{2}\right) & \text { and } \quad \zeta(\cdot, t) \equiv 0 \quad \text { outside of } B_{\rho}\left(x_{0}\right) \\
0 \leq|D \zeta| \leq \frac{1}{\rho-r}, & 0 \leq\left|\zeta_{t}\right| \leq \frac{1}{(\rho-r)^{2}} \frac{\lambda\left(B_{\rho}\left(x_{0}\right)\right)}{|\mu|_{\lambda}\left(B_{\rho}\left(x_{0}\right)\right)}
\end{array}
$$

in such a way that both the quantities in (7) are controlled by the same bound

$$
\frac{1}{(\rho-r)^{2}} \lambda\left(B_{\rho}\left(x_{0}\right)\right)
$$

By $\sim$ we mean that $t_{2}-t_{1}$ has to be proportional to $\frac{|\mu|_{\lambda}\left(B_{\rho}\left(x_{0}\right)\right)}{\lambda\left(B_{\rho}\left(x_{0}\right)\right)} \rho^{2}$.
Notice that also test functions $\zeta$ independent of time are admitted. Anyway for a detailed and clearer definition of the De Giorgi class we refer to [7]. From now on we will denote by $h$ the following function

$$
h\left(x_{0}, \rho\right):=\frac{|\mu|_{\lambda}\left(B_{\rho}\left(x_{0}\right)\right)}{\lambda\left(B_{\rho}\left(x_{0}\right)\right)} .
$$

In this way the choice of $\zeta$ (which depends on its support) will be done in such a way that $0 \leq\left|\zeta_{t}\right| \leq \frac{1}{(\rho-r)^{2}} \frac{1}{h\left(x_{0}, \rho\right)}$ and

$$
t_{2}-t_{1} \sim h\left(x_{0}, \rho\right) \rho^{2}
$$

4. Local boundedness. Here we state one of the principal results contained in [7], a result which show local boundedness of a function belonging to $D G(\Omega, T, \mu, \lambda, \gamma)$.

Theorem 4.1. Suppose $u \in D G(\Omega, T, \mu, \lambda, \gamma)$ and consider $\left(x_{0}, t_{0}\right) \in \Omega \times(0, T)$. Then there is a constant $c_{\infty}$ depending only on $\gamma, \gamma_{1}, \kappa\left(\gamma_{1}, \kappa\right.$ appearing in (3)) such that:
i) for every $B_{R}\left(x_{0}\right) \times\left(t_{0}, t_{0}+h\left(x_{0}, R\right) R^{2}\right) \subset \Omega \times(0, T)$ if $\mu_{+}\left(B_{R}\left(x_{0}\right)\right)>0$ we have $\operatorname{ess} \sup _{B_{R / 2}^{+}\left(x_{0}\right) \times\left(t_{0}+\frac{1}{2} h\left(x_{0}, R\right) R^{2}, t_{0}+h\left(x_{0}, R\right) R^{2}\right)}|u| \leq$

$$
\begin{aligned}
& \leq c_{\infty}\left[\frac{1}{h\left(x_{0}, R\right) R^{2}|\mu|_{\lambda}\left(B_{R}\left(x_{0}\right)\right)} \iint_{B_{\frac{3 R}{2}}^{+}\left(x_{0}\right) \times\left(t_{0}, t_{0}+h\left(x_{0}, R\right) R^{2}\right)} u^{2} \mu_{+} d x d t+\right. \\
& \left.\quad+\frac{1}{h\left(x_{0}, R\right) R^{2} \lambda\left(B_{R}\left(x_{0}\right)\right)} \iint_{B_{\frac{3 R}{2}}^{+}\left(x_{0}\right) \times\left(t_{0}, t_{0}+h\left(x_{0}, R\right) R^{2}\right)} u^{2} \lambda_{+} d x d t\right]^{1 / 2}
\end{aligned}
$$

ii) for every $B_{R}\left(x_{0}\right) \times\left(t_{0}-h\left(x_{0}, R\right) R^{2}, t_{0}\right) \subset \Omega \times(0, T)$ if $\mu_{-}\left(B_{R}\left(x_{0}\right)\right)>0$ we have $\operatorname{ess}_{\sup _{B_{R / 2}}^{-}\left(x_{0}\right) \times\left(t_{0}-h\left(x_{0}, R\right) R^{2}, t_{0}-\frac{1}{2} h\left(x_{0}, R\right) R^{2}\right)}|u| \leq$

$$
\begin{aligned}
& \leq c_{\infty}\left[\frac{1}{h\left(x_{0}, R\right) R^{2}|\mu|_{\lambda}\left(B_{R}\left(x_{0}\right)\right)} \iint_{B_{\frac{3 R}{2}}^{-}\left(x_{0}\right) \times\left(t_{0}-h\left(x_{0}, R\right) R^{2}, t_{0}\right)} u^{2} \mu_{-} d x d t+\right. \\
& \left.\quad+\frac{1}{h\left(x_{0}, R\right) R^{2} \lambda\left(B_{R}\left(x_{0}\right)\right)} \iint_{B_{\frac{3 R}{2}}^{-}\left(x_{0}\right) \times\left(t_{0}-h\left(x_{0}, R\right) R^{2}, t_{0}\right)} u^{2} \lambda_{-} d x d t\right]^{1 / 2} ;
\end{aligned}
$$

iii) for every $B_{R}\left(x_{0}\right) \times\left(\sigma_{1}, \sigma_{2}\right) \subset \Omega \times(0, T), \sigma_{2}-\sigma_{1}=R^{2}$, if $\lambda_{0}\left(B_{R}^{0}\left(x_{0}\right)\right)>0$

$$
\operatorname{ess} \sup _{B_{R / 2}^{0}\left(x_{0}\right) \times\left(\sigma_{1}, \sigma_{2}\right)}|u| \leq c_{\infty}\left(\frac{1}{R^{2} \lambda\left(B_{R}\left(x_{0}\right)\right)} \iint_{B_{\frac{3 R}{2}}^{0}\left(x_{0}\right) \times\left(\sigma_{1}, \sigma_{2}\right)} u^{2} \lambda_{0} d x d t\right)^{1 / 2}
$$

In the following picture there is an example of the sets involved in the previous statement in the case $\mu \neq 0$.


Figure 1. The sets involved in the estimates of points $i)$ and $i i$ ) of Theorem 4.1
5. The Harnack type inequality. In this section we state two results, the first of which is the main result of [7].

Notice the dependence of the constants $c_{+}, c_{-}, c_{0}$ : they depend on many parameters, but we want to remark here that if

$$
\lambda \equiv 1 \quad \text { and } \quad \mu \quad \text { takes values in the set }\{-1,0,1\}
$$

than

$$
K_{1}=K_{2}=K_{3}=\tau=\kappa=\varsigma=1
$$

and for every $x \in \Omega$ and every $\rho>0$ such that $B_{\rho}(x) \subset \Omega$ we have

$$
h(x, \rho)=1
$$

Theorem 5.1. Assume $u \in D G(\Omega, T, \mu, \lambda, \gamma), u \geq 0,\left(x_{o}, t_{o}\right) \in \Omega \times(0, T)$ and fix $\rho>0$.
i) Suppose $x_{o} \in \Omega_{+} \cup I_{+}$. For every $\vartheta^{+} \in(0,1]$ for which $B_{5 \rho}\left(x_{o}\right) \times\left[t_{o}-\right.$ $\left.h\left(x_{o}, \rho\right) \rho^{2}, t_{o}+16 h\left(x_{o}, 4 \rho\right) \rho^{2}+\vartheta^{+} h\left(x_{o}, \rho\right) \rho^{2}\right] \subset \Omega \times(0, T)$ there exists $c_{+}>0$ depending (only) on $\gamma_{1}, \gamma, \mathfrak{q}, \kappa, \alpha, \kappa, \tau, K_{1}, K_{2}, K_{3}, q, \varsigma, \vartheta^{+}, \rho$ such that

$$
u\left(x_{o}, t_{o}\right) \leq c_{+} \inf _{B_{\rho}^{+}\left(x_{o}\right)} u\left(x, t_{o}+\vartheta^{+} \rho^{2} h\left(x_{o}, \rho\right)\right)
$$

ii) Suppose $x_{o} \in \Omega_{-} \cup I_{-}$. For every $\vartheta^{-} \in(0,1]$ for which $B_{5 \rho}\left(x_{o}\right) \times\left[t_{o}-\right.$ $\left.16 h\left(x_{o}, 4 \rho\right) \rho^{2}+\vartheta^{-} h\left(x_{o}, \rho\right) \rho^{2}, t_{o}+h\left(x_{o}, \rho\right) \rho^{2}\right] \subset \Omega \times(0, T)$ there exists $c_{-}>0$ depending (only) on $\gamma_{1}, \gamma, \mathfrak{q}, \kappa, \alpha, \kappa, \tau, K_{1}, K_{2}, K_{3}, q, \varsigma, \vartheta^{-}, \rho$ such that

$$
u\left(x_{o}, t_{o}\right) \leq c_{-} \inf _{B_{\rho}^{-}\left(x_{o}\right)} u\left(x, t_{o}-\vartheta^{-} \rho^{2} h\left(x_{o}, \rho\right)\right)
$$

iii) Suppose $x_{o} \in \Omega_{0} \cup I_{0}$. Suppose $B_{5 \rho}\left(x_{o}\right) \subset \Omega$. Then there is $c_{0}$ depending (only) on $K_{1}, K_{2}, K_{3}, q, \varsigma, \kappa, \gamma_{1}, \gamma, \mathfrak{q}, \rho$ such that for almost every $t \in(0, T)$

$$
\sup _{B_{\rho}^{0}\left(x_{o}\right)} u(\cdot, t) \leq c_{0} \inf _{B_{\rho}^{0}\left(x_{o}\right)} u(\cdot, t)
$$

One can also prove the following theorems, which can be derived as a consequence of Theorem 5.1.

Theorem 5.2. Assume $u \in D G(\Omega, T, \mu, \lambda, \gamma), u \geq 0,\left(x_{o}, t_{o}\right) \in \Omega \times(0, T)$ and fix $\rho>0$.
i) Suppose $x_{o} \in \Omega_{+} \cup I_{+}$. For every $\vartheta^{+} \in(0,1]$ for which $B_{5 \rho}\left(x_{o}\right) \times\left[t_{o}-\right.$ $\left.16 h\left(x_{o}, 4 \rho\right) \rho^{2}+\vartheta^{-} h\left(x_{o}, \rho\right) \rho^{2}, t_{o}+h\left(x_{o}, \rho\right) \rho^{2}\right] \subset \Omega \times(0, T)$ there exists $c_{+}>0$ depending (only) on $\gamma_{1}, \gamma, \mathfrak{q}, \kappa, \alpha, \kappa, \tau, K_{1}, K_{2}, K_{3}, q, \varsigma, \vartheta^{+}, \rho$ such that

$$
c_{+} \sup _{B_{\rho}^{+}\left(x_{o}\right)} u\left(x, t_{o}-\vartheta^{+} \rho^{2} h\left(x_{o}, \rho\right)\right) \leq u\left(x_{o}, t_{o}\right)
$$

ii) Suppose $x_{o} \in \Omega_{-} \cup I_{-}$. For every $\vartheta^{-} \in(0,1]$ for which $B_{5 \rho}\left(x_{o}\right) \times\left[t_{o}-\right.$ $\left.h\left(x_{o}, \rho\right) \rho^{2}, t_{o}+16 h\left(x_{o}, 4 \rho\right) \rho^{2}+\vartheta^{+} h\left(x_{o}, \rho\right) \rho^{2}\right] \subset \Omega \times(0, T)$ there exists $c_{-}>0$ depending (only) on $\gamma_{1}, \gamma, \mathfrak{q}, \kappa, \alpha, \kappa, \tau, K_{1}, K_{2}, K_{3}, q, \varsigma, \vartheta^{-}, \rho$ such that

$$
c_{-} \sup _{B_{\rho}^{-}\left(x_{o}\right)} u\left(x, t_{o}-\vartheta^{-} \rho^{2} h\left(x_{o}, \rho\right)\right) \leq u\left(x_{o}, t_{o}\right) .
$$

Corollary 1. Under the same assumptions of Theorem 5.1, fix $R>0$. Then
i) there is $c_{+}$, depending on the same constants (but $\rho$ ) as above and on $R$, such that

$$
u\left(x_{o}, t_{o}\right) \leq c_{+} \inf _{P_{R, \vartheta+}^{+}\left(x_{o}, t_{o}\right)} u
$$

where

$$
P_{R, \vartheta^{+}}^{+}\left(x_{o}, t_{o}\right)=\bigcup_{\rho \in(0, R]} B_{\rho}^{+}\left(x_{o}\right) \times\left\{t_{o}+\vartheta^{+} \rho^{2} h\left(x_{o}, \rho\right)\right\}
$$

ii) there is $c_{-}$, depending on the same constants (but $\rho$ ) as above and on $R$, such that

$$
u\left(x_{o}, t_{o}\right) \leq c_{-} \inf _{P_{R, \vartheta^{-}}^{-}\left(x_{o}, t_{o}\right)} u
$$

where

$$
P_{R, \vartheta^{-}}^{-}\left(x_{o}, t_{o}\right)=\bigcup_{\rho \in(0, R]} B_{\rho}^{-}\left(x_{o}\right) \times\left\{t_{o}-\vartheta^{-} \rho^{2} h\left(x_{o}, \rho\right)\right\}
$$

Proof. The proof is immediate since it is sufficient considering, for point $i$ ) for instance, for each $\rho \in(0, R]$ the constant $c_{+}$of Theorem 5.1 and then taking the supremum with respect to $\rho \in(0, R]$. Notice that also $\rho=0$ can be considered, but in that case the inequality becomes trivial with $c_{+}=1$, so in fact one is taking the supremum with respect to $\rho$ in the compact $[0, R]$.

Corollary 2. Under the same assumptions of Theorem 5.1
i) for every $\vartheta_{1}^{+}, \vartheta_{2}^{+}$with $0<\vartheta_{1}^{+}<\vartheta_{2}^{+}$one has $c_{+}$, depending on the same constants as above and moreover on $\vartheta_{1}^{+}, \vartheta_{2}^{+}$, such that
$\sup _{B_{\rho}^{+}\left(x_{o}\right) \times\left(t_{o}-\vartheta_{2}^{+} \rho^{2} h\left(x_{o}, \rho\right), t_{o}-\vartheta_{1}^{+} \rho^{2} h\left(x_{o}, \rho\right)\right)} u \leq c_{+} \inf _{B_{\rho}^{+}\left(x_{o}\right) \times\left(t_{o}+\vartheta_{1}^{+} \rho^{2} h\left(x_{o}, \rho\right), t_{o}+\vartheta_{2}^{+} \rho^{2} h\left(x_{o}, \rho\right)\right)} u ;$
ii) for every $\vartheta_{1}^{-}, \vartheta_{2}^{-}$with $0<\vartheta_{1}^{-}<\vartheta_{2}^{-}$one has $c_{-}$, depending on the same constants as above and moreover on $\vartheta_{1}^{-}, \vartheta_{2}^{-}$, such that
$\sup _{B_{\rho}^{-}\left(x_{o}\right) \times\left(t_{o}+\vartheta_{1}^{-} \rho^{2} h\left(x_{o}, \rho\right), t_{o}+\vartheta_{2}^{-} \rho^{2} h\left(x_{o}, \rho\right)\right)} u \leq c_{-} \inf _{B_{\rho}^{-}\left(x_{o}\right) \times\left(t_{o}-\vartheta_{2}^{-} \rho^{2} h\left(x_{o}, \rho\right), t_{o}-\vartheta_{1}^{-} \rho^{2} h\left(x_{o}, \rho\right)\right)} u$.
The following result is an evident consequence of Theorem 5.1, but we state it to show expressly the Harnack type inequality in a point $x_{o}$ belonging to the interface I.

Theorem 5.3. Assume $u \in D G(\Omega, T, \mu, \lambda, \gamma), u \geq 0$. Fix $\rho>0$ and $\vartheta \in$ $(0,1]$ for which $B_{5 \rho}\left(x_{o}\right) \times\left[t_{o}-16 h\left(x_{o}, 4 \rho\right) \rho^{2}-\vartheta h\left(x_{o}, \rho\right) \rho^{2}, t_{o}+16 h\left(x_{o}, 4 \rho\right) \rho^{2}+\right.$ $\left.\vartheta h\left(x_{o}, \rho\right) \rho^{2}\right] \subset \Omega \times(0, T)$. Suppose $x_{o} \in I$. Then there exists $c>0$ depending on $\gamma_{1}, \gamma, \mathfrak{q}, \kappa, \alpha, \kappa, \tau, K_{1}, K_{2}, K_{3}, q, \varsigma, \vartheta, \rho$ such that

$$
u\left(x_{o}, t_{o}\right) \leq c \inf _{B_{\rho}\left(x_{o}\right)} \tilde{u}(x)
$$

where

$$
\tilde{u}(x)=\left\{\begin{array}{ll}
u\left(x, t_{o}+\vartheta h\left(x_{o}, \rho\right) \rho^{2}\right) & \text { if } x \in B_{\rho}^{+}\left(x_{o}\right) \\
u\left(x, t_{o}-\vartheta h\left(x_{o}, \rho\right) \rho^{2}\right) & \text { if } x \in B_{\rho}^{-}\left(x_{o}\right) \\
u\left(x, t_{o}\right) & \text { if } x \in B_{\rho}^{0}\left(x_{o}\right)
\end{array} \quad\left(x_{o} \in I\right)\right.
$$

Comments. If $\mu>0$ almost everywhere Theorem 5.1 and Corollary 2 reduces to point $i$ ) which is a standard parabolic Harnack's inequality which, only for the solutions and not for the De Giorgi class, of linear equations is contained in the paper [4].

Clearly if $\mu<0$ almost everywhere we have the analogous result for backward parabolic equations.

Finally if $\mu \equiv 0$ we have a family of elliptic Harnack's inequalities, which gives a regularity (only in space) result which generalizes the one contained in [1].

## 6. Some consequences: Hölder continuity and a maximum principle.

Local Hölder-continuity. Mimicking the Moser's proof of local Hölder estimates derived from the elliptic Harnack's inequality (see, e.g., the comments in Chapter 7 in [3]) one can get from Theorem 5.1, Corollary 2 and Theorem 5.3 the local Hölder continuity for the functions in $D G(\Omega, T, \mu, \lambda, \gamma)$. Precisely one gets that

$$
u \text { is locally Hölder continuous in }\left(\Omega_{+} \cup \Omega_{-}\right) \times(0, T)
$$

and for almost every $t \in(0, T)$

$$
u(\cdot, t) \text { is locally Hölder continuous in } \Omega_{0} .
$$

One in particular gets (by Corollary 2) that

$$
u \text { is Hölder continuous in } I \times(0, T) \text {, }
$$

while to get continuity in time in $\Omega_{0} \times(0, T)$ is hopeless as the following example shows.

Consider $n=1, \Omega=(0,1)$ and the solution of the problem

$$
\begin{cases}\frac{d^{2} u}{d x^{2}}=0 & \text { in } \Omega \times(0, T) \\ u(0, t)=0 & \text { for } t \in[0, T] \\ u(0, t)=1 & \text { for } t \in[0, T / 2) \\ u(0, t)=2 & \text { for } t \in[T / 2, T]\end{cases}
$$

The solution is given by

$$
u(x, t)=x \quad \text { in } \Omega \times[0, T / 2) \quad \text { and } \quad u(x, t)=2 x \quad \text { in } \Omega \times[T / 2, T]
$$

which belong to the De Giorgi class defined in Definition 3.1 and which clearly is discontinuous in $t=T / 2$.

A "local" maximum principle. First we give a partial result for points belonging to the interface $I$ defined in (5).

In [7] the following fact is proved (see Remark 2.7): for every $x \in \Omega, r, R>0$ for which $r<R$ and $B_{R}(x) \subset \Omega$ one has that the function

$$
\tilde{f}(x, \rho)=\rho^{2 \tilde{\alpha}} h(x, \rho)=\rho^{2 \tilde{\alpha}} \frac{|\mu|_{\lambda}\left(B_{\rho}(x)\right)}{\lambda\left(B_{\rho}(x)\right)},
$$

where $\tilde{\alpha}<1$ is the constant appearing in (H.2)', satisfies

$$
\tilde{f}(x, r)=r^{2 \tilde{\alpha}} h(x, r) \leq \tilde{K}_{2}^{2} R^{2 \tilde{\alpha}} h(x, R)=\tilde{K}_{2}^{2} \tilde{f}(x, R) .
$$

By that we derive that

$$
\limsup _{\rho \rightarrow 0^{+}} \tilde{f}(x, \rho)<+\infty
$$

and in particular

$$
\begin{equation*}
\lim _{\rho \rightarrow 0^{+}} f(x, \rho)=0 \quad \text { where } \quad f(x, \rho):=\rho^{2} h(x, \rho) \tag{8}
\end{equation*}
$$

Moreover notice that for every $x \in \Omega$

$$
\rho \mapsto \tilde{f}(x, \rho) \quad \text { is continuous in }(0, R]
$$

and, by (8), one gets that

$$
\begin{equation*}
\rho \mapsto f(x, \rho) \quad \text { is continuous in }[0, R] \quad \text { and } f(x, 0)=0 \tag{9}
\end{equation*}
$$

but not necessarily increasing.
Thanks to (9) the sets $P_{R, \vartheta^{+}}^{+}$and $P_{R, \vartheta^{-}}^{-}$(defined in Corollary 1) could be like the example in the following picture, where for simplicity we have chosen $n=1$, $\left(x_{o}, t_{o}\right)=(0,0), \mu>0$ for $x<0$ and $\mu<0$ for $x>0$.

Now consider $\left(x_{o}, t_{o}\right)((0,0)$ in the picture) and suppose

$$
\left(x_{o}, t_{o}\right) \in I \times(0, T)
$$


is a maximum point. In particular it is a local maximum point and then for every $\rho>0$ such that

$$
B_{5 \rho}\left(x_{o}\right) \times\left[t_{o}-17 h\left(x_{o}, 4 \rho\right) \rho^{2}, t_{o}+17 h\left(x_{o}, \rho\right) \rho^{2}\right] \subset \Omega \times(0, T)
$$

there is $\delta>0$ such that

$$
M=u\left(x_{o}, t_{o}\right) \geq u(x, t) \quad \text { for every }(x, y) \in B_{\rho}\left(x_{o}\right) \times\left(t_{o}-\delta, t_{o}+\delta\right) .
$$

Then, once defined $v:=M-u$, since $v \in D G(\Omega, T, \mu, \lambda, \gamma)$ for some $\gamma>0, v \geq 0$ in $B_{\rho}\left(x_{o}\right) \times\left(t_{o}-\delta, t_{o}+\delta\right), M-u\left(x_{o}, t_{o}\right)=0$, applying Corollary 1 with $\vartheta=\vartheta^{+}=\vartheta^{-}$ and Theorem 5.1, point iii), we get that there is $c$, depending in particular on $\vartheta$, such that

$$
v\left(x_{o}, t_{o}\right) \leq c \inf _{C_{p, \delta}^{\theta}\left(x_{o}, t_{o}\right)} v
$$

where $c=\max \left\{c_{+}, c_{-}, c_{0}\right\}$ and

$$
\begin{aligned}
& C_{\rho, \delta}^{\vartheta}\left(x_{o}, t_{o}\right):= \\
:= & \left(\left(P_{R, \vartheta}^{+}\left(x_{o}, t_{o}\right) \cup P_{R, \vartheta}^{-}\left(x_{o}, t_{o}\right)\right) \cap\left(B_{\rho}\left(x_{o}\right) \times\left(t_{o}-\delta, t_{o}+\delta\right)\right)\right) \cup\left(B_{\rho}^{0}\left(x_{o}\right) \times\left\{t_{o}\right\}\right) .
\end{aligned}
$$

Then we deduce that

$$
\begin{equation*}
v=0 \quad \text { in } C_{\rho, \delta}^{\vartheta}\left(x_{o}, t_{o}\right) \tag{10}
\end{equation*}
$$

provided that assumptions of Theorem 5.1 are satisfied, i.e.

$$
B_{5 \rho}\left(x_{o}\right) \times\left[t_{o}-17 h\left(x_{o}, 4 \rho\right) \rho^{2}, t_{o}+17 h\left(x_{o}, \rho\right) \rho^{2}\right] \subset \Omega \times(0, T) .
$$

Now fix a point

$$
(\bar{x}, \bar{t}) \in\left(B_{\rho}^{+}\left(x_{o}\right) \times\left(t_{o}, t_{o}+\delta\right)\right) \cup\left(B_{\rho}^{-}\left(x_{o}\right) \times\left(t_{o}-\delta, t_{o}\right)\right) .
$$

Since (10) is true for every $\vartheta>0$, taking $\vartheta$ small enough it is possible to get that $(\bar{x}, \bar{t}) \in C_{\rho, \delta}^{\vartheta}\left(x_{o}, t_{o}\right)$ for some $\vartheta$, and then conclude that $v(\bar{x}, \bar{t})=0$, i.e. $u(\bar{x}, \bar{t})=M$. Then one can conclude that

$$
\begin{equation*}
\text { if } x_{o} \in I \text { is such that }\left(x_{o}, t_{o}\right) \text { is a maximum point, } u\left(x_{o}, t_{o}\right)=M \text {, } \tag{11}
\end{equation*}
$$

then there are $\rho, \delta>0$ such that

$$
\text { then } \begin{aligned}
& u(x, t)=M \text { in } \quad\left(B_{\rho}^{+}\left(x_{o}\right) \times\left(t_{o}-\delta, t_{o}\right)\right) \cup\left(B_{\rho}^{-}\left(x_{o}\right) \times\left(t_{o}, t_{o}+\delta\right)\right) \cup \\
& \cup\left(B_{\rho}^{0}\left(x_{o}\right) \times\left\{t_{o}\right\}\right) .
\end{aligned}
$$

The analogous result holds if $\left(x_{o}, t_{o}\right)$ is a minimum point.

A maximum principle. Now consider

$$
\left(x_{o}, t_{o}\right) \in \Omega \times(0, T)
$$

and suppose it is a maximum point for a function $u \in D G(\Omega, T, \mu, \lambda, \gamma), u\left(x_{o}, t_{o}\right)=$ $M$. We suppose here that $\Omega$ is connected and, for simplicity, that $\Omega_{+}, \Omega_{-}, \Omega_{0}$ are connected, but one could consider the more general case described in (6).

1. Suppose first that

$$
x_{o} \in \Omega_{+} .
$$

Since in particular

$$
u \in D G\left(\Omega_{+}, T, \mu, \lambda, \gamma\right)
$$

which is a parabolic (forward-parabolic) De Giorgi class. By point $i$ ) of Theorem 5.2 combined with the argument used to show the "local" maximum principle we get that there are $\rho>0$ and $\delta>0$ such that

$$
\begin{equation*}
B_{\rho}\left(x_{o}\right) \times\left(t_{o}-\delta, t_{o}\right) \subset \Omega_{+} \times\left(0, t_{o}\right), \quad u \equiv M \quad \text { in } B_{\rho}\left(x_{o}\right) \times\left(t_{o}-\delta, t_{o}\right) . \tag{12}
\end{equation*}
$$

Now consider the set

$$
C_{M}:=\left\{(x, t) \in \Omega_{+} \times\left(0, t_{o}\right] \mid u(x, t)=M\right\}
$$

which, by the continuity of $u$ (see the first subsection of the present section) has to be a closed subset of $\Omega_{+} \times\left(0, t_{o}\right]$ (closed in the topology induced in $\Omega_{+} \times\left(0, t_{o}\right.$ ] by $\mathbf{R}^{n+1}$ ), but because of (12) we have

$$
C_{M} \supsetneq\left\{\left(x_{o}, t_{o}\right)\right\} .
$$

Now suppose, by contradiction, that $C_{M}$ is strictly included in $\Omega_{+} \times\left(0, t_{o}\right]$. If this were true, since $C_{M}$ is closed we could find a point $(\bar{x}, \bar{t})$,

$$
(\bar{x}, \bar{t}) \in \partial C_{M}
$$

(notice that this is a maximum point for $u$ ) for which one could repeat the argument as before and find $r>0$ and $\varepsilon>0$ such that

$$
\begin{aligned}
& B_{r}(\bar{x}) \times(\bar{t}-\varepsilon, \bar{t}) \subset \Omega_{+} \times(0, \bar{t}), \\
& B_{r}(\bar{x}) \times(\bar{t}-\varepsilon, \bar{t}) \nsubseteq C_{M}
\end{aligned} \quad u \equiv M \quad \text { in } B_{r}(\bar{x}) \times(\bar{t}-\varepsilon, \bar{t}),
$$

but this would be impossible. Then

$$
C_{M}=\Omega_{+} \times\left(0, t_{o}\right]
$$

As a consequence one gets in particular that

$$
u=M \quad \text { in } I_{+} \times\left(0, t_{o}\right] .
$$

If $\Omega_{+}=\Omega$ we have nothing else to prove, otherwise $I_{+} \cap\left(I_{-} \cup I_{0}\right) \neq \emptyset$ and

$$
u=M \quad \text { in } I_{+} \cap\left(I_{-} \cup I_{0}\right) \times\left(0, t_{o}\right] .
$$

Then we can find a point

$$
\bar{x} \in I_{+} \cap\left(I_{-} \cup I_{0}\right)
$$

1.1. Suppose first

$$
I_{+} \cap I_{-} \neq \emptyset
$$

Then $\bar{x} \in I_{-}$. Then for every $s \in\left(0, t_{o}\right]$ we can repeat the argument as above and in an analogous way we get that

$$
u=M \quad \text { in } \Omega_{-} \times[s, T)
$$

for every $s>0$, and then

$$
u=M \quad \text { in } \Omega_{-} \times(0, T)
$$

Since in particular we have

$$
u=M \quad \text { in }\left(\partial \Omega_{-} \cap \partial \Omega_{+}\right) \times(0, T)
$$

we can also derive with the usual argument that

$$
u=M \quad \text { in } \Omega_{+} \times(0, T)
$$

Then finally we conclude that

$$
u=M \quad \text { in }\left(\Omega_{+} \cap \Omega_{-}\right) \times(0, T)
$$

1.2. Suppose now

$$
I_{+} \cap I_{0} \neq \emptyset
$$

Then by (11) and the classical argument (see, e.g., Theorem 7.12 in [3]) we derive that

$$
\begin{equation*}
u=M \quad \text { in }\left(\Omega_{+} \cup \Omega_{0}\right) \times\left(0, t_{o}\right] \tag{13}
\end{equation*}
$$

Now if

$$
I_{0} \cap I_{-} \neq \emptyset
$$

then we can argue as in point $\mathbf{1 . 1}$ and conclude first that

$$
u=M \quad \text { in } \Omega_{-} \times(0, T)
$$

and finally

$$
u=M \quad \text { in } \Omega \times(0, T),
$$

otherwise only (13) holds.
2. If $x_{o} \in \Omega_{-}$we can argue similarly as before. Suppose now

$$
x_{o} \in \Omega_{0} \backslash I
$$

Then, since $u$ is continuous, we conclude (see, e.g., Theorem 7.12 in [3]) that

$$
u\left(\cdot, t_{o}\right)=M \quad \text { in } \Omega_{0}
$$

If $\Omega_{0}=\Omega$ we can prove nothing else, but if

$$
I_{0} \cap I_{+} \neq \emptyset \quad \text { or } \quad I_{0} \cap I_{-} \neq \emptyset
$$

we reach the boundary of $\Omega_{+}$or of $\Omega_{-}$and using the local result and arguing as in point 1.1 we get something more. Precisely

$$
\begin{array}{cccc}
I_{0} \cap I_{+} \neq \emptyset \quad \Longrightarrow \quad u=M & \text { in }\left(\Omega_{+} \cup \Omega_{0}\right) \times\left(0, t_{o}\right], \\
I_{0} \cap I_{-} \neq \emptyset \quad \Longrightarrow \quad u=M & \text { in }\left(\Omega_{-} \cup \Omega_{0}\right) \times\left[t_{o}, T\right), \\
I_{0} \cap I_{+} \neq \emptyset \text { and } I_{0} \cap I_{-} \neq \emptyset & \Longrightarrow & u=M \quad \text { in } \Omega \times(0, T) .
\end{array}
$$

Combining these informations if $\Omega_{+} \neq \emptyset, \Omega_{-} \neq \emptyset, \Omega_{0} \neq \emptyset$ one can reach that

$$
u=M \quad \text { in } \Omega \times(0, T)
$$

3. If $x_{o} \in I$ we can use the local maximum principle to find an open set in which $u$ is constant, then proceed as above.

The same conclusions hold if $\left(x_{o}, t_{o}\right)$ is a minimum point.
Summing up the following result holds.
Theorem 6.1. Suppose $\Omega, \Omega_{+}, \Omega_{-}, \Omega_{0}$ are connected. Consider $u \in D G(\Omega, T, \mu, \lambda$, $\gamma$ ) and suppose $\left(x_{o}, t_{o}\right) \in \Omega \times(0, T)$ is a maximum (or a minimum) point for $u$ in $\Omega \times(0, T)$. Then
i) if $\Omega_{+} \neq \emptyset, \Omega_{-}=\emptyset$, then $u$ is constant in $\Omega \times\left(0, t_{o}\right]$;
ii) if $\Omega_{+}=\emptyset, \Omega_{-} \neq \emptyset$, then $u$ is constant in $\Omega \times\left[t_{o}, T\right)$;
iii) if $\Omega_{+}=\emptyset, \Omega_{-}=\emptyset, \Omega_{0} \neq \emptyset$ then $u$ is constant in $\Omega \times\left\{t_{o}\right\}$;
iv) if $\Omega_{+} \neq \emptyset, \Omega_{-} \neq \emptyset$, then $u$ is constant in $\Omega \times(0, T)$.

Notice that points $i$ ), ii), $i v)$ are independent of $\Omega_{0}$ : this could be empty or not.

One can adapt this result to a more general result in which each set among $\Omega_{+}$, $\Omega_{-}, \Omega_{0}$ can have more than one connected component, as assumed in (6).


Example. Here we give an example to show that point $i i i$ ) of the previous theorem is sharp, in the sense that the conclusion, in general, is the best one can get. Consider the family of elliptic problems

$$
\begin{cases}\frac{d^{2} u}{d x^{2}}(x, t)=0 & \text { in }(-1,1) \times(0,2 \pi) \\ u(-1, t)=2 \sin t & t \in(0,2 \pi) \\ u(1, t)=2 & t \in(0,2 \pi)\end{cases}
$$

whose solution is

$$
u(x, t)=(1-\sin t) x+1+\sin t
$$

This function has a maximum point in $(0, \pi / 2)$. It is constant in $(-1,1) \times\{\pi / 2\}$, but it not constant in no other bigger set.

Example. We conclude with an example of a possible interface to explain assumptions (H.4). Suppose $\Omega \subset \mathbf{R}^{2}$ and suppose $I$ is the image of a curve, which has a cusp. Assuming, for simplicity, that $\mu$ takes only the two values 1 and -1 , in this case not always the Lebesgue measure restricted to one of the two part of $\Omega$ delineated by the curve satisfies (H.4). Suppose the curve below if the union of the graphs of two functions $f$ and $g$. For instance, if $f(x)=x^{n}$ and $g(x)=-x^{n}(x \geq 0)$ assumption (H.4) is satisfied, if $f(x)=e^{-\frac{1}{x}}$ and $g(x)=-e^{-\frac{1}{x}} \quad(x>0)$ assumption (H.4) is not.

In the first case $I$ is an admitted interface, and so the Harnack inequality and all the consequences hold, in the second case $I$ is not an admitted interface, but we do not know if in such a case Harnack's inequality fails to hold.

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