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Integrated likelihoods in parametric survival models for highly-stratified censored data

Giuliana Cortese · Nicola Sartori

Abstract In studies that involve censored time-to-event data, stratification is frequently encountered due to different reasons, like stratified sampling or model adjustment due to violation of model assumptions. Often, the main interest is not in the stratification variables, and the stratum-related parameters are treated as nuisance. When inference is about a parameter of interest in presence of many nuisance parameters, standard likelihood methods often perform very poorly and may lead to severe bias. For stratified data, this problem is particularly evident in models with stratum nuisance parameters when the number of strata is relatively high with respect to the within-stratum size. However, it is still unclear how the presence of censoring would affect this issue. We consider stratified failure time data in a parametric framework, and propose frequentist inference based on an integrated likelihood. Moreover, we then apply the proposed approach to a stratified Weibull model. Simulation studies show that appropriately defined integrated likelihoods provide very accurate inferential results in all circumstances, like for highly stratified data or heavy censoring, even in extreme settings where standard likelihoods lead to strongly misleading results. An application, which concerns treatments for a frequent disease in late-stage HIV-infected people, illustrates the proposed inferential method in Weibull regression models, and warns against different inferential conclusions when integrated and profile likelihoods are used.

Keywords Integrated likelihood · Profile Likelihood · Time-to-event data · Stratification · Stratum nuisance parameters · Weibull model.

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Abstract  In studies that involve censored time-to-event-data, stratification is frequently encountered due to different reasons, like stratified sampling or model adjustment due to violation of model assumptions. Often, the main interest is not in the stratification variables, and the stratum-related parameters are treated as nuisance. When inference is about a parameter of interest in presence of many nuisance parameters, standard likelihood methods often perform very poorly and may lead to severe bias. For stratified data, this problem is particularly evident in models with stratum nuisance parameters when the number of strata is relatively high with respect to the within-stratum size. However, it is still unclear how the presence of censoring would affect this issue. We consider stratified failure time data in a parametric framework, and propose frequentist inference based on an integrated likelihood. Moreover, we then apply the proposed approach to a stratified Weibull model. Simulation studies show that appropriately defined integrated likelihoods provide very accurate inferential results in all circumstances, like for highly stratified data or heavy censoring, even in extreme settings where standard likelihoods lead to strongly misleading results. An application, which concerns treatments for a frequent disease in late-stage HIV-infected people, illustrates the proposed inferential method in Weibull regression models, and warns against different inferential conclusions when integrated and profile likelihoods are used.

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1 Introduction

Stratified settings are frequently encountered in studies that involve time-to-event data subject to censoring. Stratified censored data appears often in different applied contexts, ranging from biomedicine and health science, to economics, engineering and reliability. Examples of stratification variables may be treatment...
regimens, geographical regions, study centers, or operating conditions, materials
and measuring methods. The needs for resorting to a stratified analysis can be of
different nature, such as presence of a stratified sampling, confounding factors, or,
alternatively, model adjustments due to violations of model assumptions. Typi-
cally, stratified models account for inter-stratum variability but the main interest
is not in studying the stratum-related parameters.

The current paper deals with parametric models for stratified censored data.
In particular, we assume a fixed effects approach, as often done for instance in
the econometric literature, where the fixed effects are stratum-specific param-
ters, while the remaining parameters, common to all strata, are considered here
as parameters of interest. A commonly used alternative formulation is given by
frailty models, where the stratum-specific effects are assumed as random effects,
independent of the measured covariates, and sampled from a given family of dis-
tributions. This approach has the advantage of parsimony, since the number of
parameters does not grow with the number of cluster, as in fixed effects models.
On the other hand, the fixed effects formulation relaxes the assumptions on the
random effects and is also an attractive approach when the cluster effects might
be of intrinsic interest at some stage in the analysis, and for model checking.

Of course, it is well known that standard likelihood inference for a parameter of
interest could be seriously misleading in the presence of many stratum-specific nuis-
ance parameters, relatively to the sample size. The main reason is that inference
is in fact based on the profile likelihood, which is simply the likelihood in which
the nuisance parameters are maximized out, for every fixed value of the parameter
of interest. The profile likelihood is not a proper likelihood. Indeed, for instance,
the corresponding score function is biased (Severini 2000, Chap. 4). While this is
not a problem in standard settings, in a stratified setting this bias may grow with
the dimension of the nuisance parameter and invalidate usual asymptotic results
(Sartori 2003).

Many alternative pseudo likelihoods have been proposed to solve this problem,
such as marginal and conditional likelihoods (see, for instance, Severini 2000, Chap.
8). The issue with these pseudo likelihoods is that their existence depends on the
model structure and, even when they exists, they may be difficult to compute.

A widely studied alternative is to consider modified profile likelihoods, which
correct for the presence of nuisance parameters (Cox and Reid 1987; Barndorff-
Nielsen and Cox 1994, Chap. 8). These likelihoods perform much better than pro-
file likelihoods in models with many nuisance parameters, in particular in stratified
models where nuisance parameters are associated to the strata (Sartori 2003; Bel-
lio and Sartori 2006; Bartolucci et al. 2014). However, in the presence of censored
data it is unclear how to compute the modified profile likelihood, especially under
general censoring and in regression settings; an example based on Monte Carlo
simulations is given in Pierce and Bellio (2006).

A recent alternative approach to the elimination of nuisance parameters, which
is the standard practice in Bayesian settings, is to summarize the proper likelihood
by averaging with respect to some weight function for the nuisance parameters. In
a frequentist setting, this method leads to a particular type of pseudo likelihood for
the parameter of interest, called the integrated likelihood function (Severini 2007,
2010, 2011). It has been shown that integrated likelihood functions may provide
an accurate approximation to modified profile likelihoods and, in some cases, may
have better properties, e.g., in presence of small sample sizes (Examples 2 and 4 in
Severini (2007), Bellio and Guolo (2014)). Furthermore, integrated likelihoods have the advantage to be always computable and available. It is therefore of interest to investigate the properties of inference based on integrated likelihoods in stratified models for censored data, especially under general censoring mechanisms. Some theoretical results and empirical evidence are given in De Bin (2012) and De Bin et al. (2014) for integrated likelihoods in models with many stratum nuisance parameters, but with no reference to survival models, nor to censored data.

The scope of the paper is then to investigate the performance of integrated likelihood functions for inference in parametric survival models for stratified censored data. We are particularly interested in settings with many strata, also in presence of heavy censoring, in order to understand their combined effect on inferential results. The inferential procedure based on integrated likelihoods is presented in the general setting of parametric survival models, under the assumption of noninformative independent censoring. Furthermore, in order to show the practical use of integrated likelihood functions, we consider an application to the stratified Weibull model, under both the assumptions of type I and random censoring. The extension to the regression setting is illustrated by means of a real data example about HIV-infected people.

Section 2 introduces the notation and describes the profile likelihood for stratified survival data. In Section 3 the integrated likelihood approach is presented for stratified survival models in a general setting under the assumption of noninformative independent censoring. Then, in Section 4 we illustrate the specific results of integrated likelihood functions for a stratified Weibull model. Monte Carlo simulations studies for both complete data and right-censored data are described in Section 5. Section 6 shows the real-data application. Finally, general remarks and possible extensions are discussed in Section 7.

2 Notation and profile likelihood

Let us assume a setting where data are stratified with \( i = 1, \ldots, n \) strata and \( j = 1, \ldots, k_i \) observations within stratum \( i \). The total sample size is \( m = \sum_{i=1}^{n} k_i \).

Suppose also that the observations are times to a certain event, denoted by \( \tilde{T}_{ij} \). Consider then a parametric model with stratified lifetimes of the form

\[
\tilde{T}_{ij} \sim p_{ij}(t_{ij}; \psi, \lambda_i),
\]

for \( i = 1, \ldots, n \) and \( j = 1, \ldots, k_i \). In the following, for ease of notation, we assume \( k_1 = \ldots = k_n = k \) so that all strata have the same size. Let the model depend on \( \theta = (\psi, \lambda) \) where \( \psi \) is a parameter of interest taking values in \( \Psi \) and \( \lambda = (\lambda_1, \ldots, \lambda_n) \) is a \( n \)-dimensional nuisance parameter. For simplicity, each stratum nuisance parameter \( \lambda_i \) is assumed to be scalar, without compromising the validity of the results in the paper. Moreover, each \( \lambda_i \) is assumed to have the same meaning and the same parameter space.

Let us define with \( \tilde{T}_i = (\tilde{T}_{i1}, \ldots, \tilde{T}_{ik_i}) \) the vector of independent within-stratum random variables. Suppose that \( \tilde{T}_1, \ldots, \tilde{T}_n \) are independent but not identically distributed because of the stratified structure and the possible presence of covariates. Denote with \( S_{ij}(t_{ij}; \psi, \lambda_i) = \Pr(\tilde{T}_{ij} > t_{ij}) \) and \( h_{ij}(t_{ij}; \psi, \lambda_i) = p_{ij}(t_{ij}; \psi, \lambda)/S_{ij}(t_{ij}; \psi, \lambda_i) \) the survival function and the hazard function of \( T_{ij} \), respectively.
Regession models that consider explanatory variables $x_{ij}$ may also be considered without additional difficulties to the theoretical aspects presented in the paper. The application in Section 6 is an example of such regression models for randomly-censored data.

Typically, time-to-event data are incomplete, i.e., observations are subject to right censoring. Let $C_{ij}$ be the censoring times with unknown density and survival functions $g_{ij}(\cdot)$ and $G_{ij}(\cdot)$, respectively. For each unit $(i,j)$ the observed data is represented by the couple $(T_{ij}, \Delta_{ij})$, where $T_{ij} = \min(T_{ij}, C_{ij})$ and $\Delta_{ij} = I(T_{ij} \leq C_{ij})$.

Let us assume independent and noninformative censoring, i.e., the censoring mechanism does not depend on the times to event nor on their distribution. Consequently, the distribution of the $C_{ij}$ does not depend on the parameters $(\psi, \lambda)$. Moreover, for ease of explanation of the proposed approach, let us consider the two alternative censoring schemes, separately: Type I censoring and random censoring.

In the former, the censoring times $c_{ij}$ are fixed in advance, and in addition values $c_1, \ldots, c_n$ may also be assumed constant across the $n$ strata, so that $C_{ij} = c_i$ for $j = 1, \ldots, k$.

Suppose that the censoring times have the same structure as the failure times and $(C_{i1}, \ldots, C_{ik})$, for $i = 1, \ldots, n$, are independent vectors of within-stratum random variables. In presence of random censoring, the joint density of $(T_{ij}, \Delta_{ij})$ depends on the distribution of $C_{ij}$ and has the form

$$f_{ij}(t_{ij}, \delta_{ij}; \theta, \nu) = p_{ij}(t_{ij}; \theta)^{\delta_{ij}} S_{ij}(t_{ij}; \theta)^{1-\delta_{ij}} G_{ij}(t_{ij})^{\delta_{ij}} g_{ij}(t_{ij})^{1-\delta_{ij}}.$$ 

For fixed censoring, the censoring probability mass function is equal to one, leading to the simpler form $f_{ij}(t_{ij}, \delta_{ij}; \theta, \nu) = p_{ij}(t_{ij}; \theta)^{\delta_{ij}} S_{ij}(t_{ij}; \theta)^{1-\delta_{ij}}$, for $t_{ij} \in (0, c_{ij}]$. Here and in the following, we assume that the $C_{ij}$ have either a nonparametric distribution $G_{ij}(\cdot)$, or a parametric distribution that depends on a parameter $\nu$, with survival and density functions denoted by $G_{ij}(\cdot; \nu)$ and $g_{ij}(\cdot; \nu)$ respectively.

In the latter case, the observed censoring time $c_{ij}$ is both a partially sufficient statistic for $\nu$ (sufficient statistic when $\theta$ is fixed) and a constant statistic for all $\theta$ (it does not depend on $\theta$ because of noninformative censoring). Thus, the $(i,j)$ contribution to the likelihood function for $\theta$ may be based on the conditional density

$$f_{T_{ij}, \Delta_{ij}|C_{ij}=c_{ij}}(t_{ij}, \delta_{ij}; c_{ij}, \theta) = p_{ij}(t_{ij}; \theta)^{\delta_{ij}} S_{ij}(t_{ij}; \theta)^{1-\delta_{ij}},$$

which does not depend on the parameter $\nu$ of the censoring distribution.

Therefore, if we assume also that $C_{i1}, \ldots, C_{ik}$ are independent, the full likelihood $L(\theta, \nu)$ is separable with respect to the parameters $\theta$ and $\nu$, and can be factorized as $L(\theta, \nu) = L(\theta) L(\nu)$. The factor $L(\theta)$ can then be used as a proper likelihood for $\theta$.

Under both fixed and random censoring assumptions, the log likelihood $\log L(\theta) = \ell(\theta) = \ell(\psi, \lambda)$ can be written as

$$\ell(\psi, \lambda) = \sum_{i=1}^{n} \ell^i(\psi, \lambda_i),$$

where the log likelihood contribution of the $i$th stratum is

$$\ell^i(\psi, \lambda_i) = \sum_{j=1}^{k} [\delta_{ij} \log h_{ij}(t_{ij}; \psi, \lambda_i) + \log S_{ij}(t_{ij}; \psi, \lambda_i)].$$
Note that the log likelihood is separable with respect to the nuisance parameters, for fixed \( \psi \), since each contribution of stratum \( i \) depends only on the corresponding stratum nuisance parameter \( \lambda_i \).

Let \( \hat{\theta} = (\hat{\psi}, \hat{\lambda}) \) be the maximum likelihood estimator of \( \theta = (\psi, \lambda) \). Standard likelihood inference for the parameter of interest \( \psi \) is based, either explicitly or implicitly, on the profile log likelihood function, which for stratified data can be given as the sum of \( n \) strata terms

\[
\ell_P(\psi) = \sum_{i=1}^{n} \ell_i(\psi, \hat{\lambda}_i) = \sum_{i=1}^{n} \ell_P(\psi).
\] (5)

The elements of \( \hat{\lambda}_\psi = (\hat{\lambda}_1, \ldots, \hat{\lambda}_n) \), the maximum likelihood estimate of \( \lambda \) for fixed \( \psi \), are the solutions to the independent likelihood estimating equations for the strata

\[
\ell_\lambda(\psi, \lambda_i) = \frac{d}{d\lambda_i} \ell(\psi, \lambda_i) = 0.
\]

The function \( \ell_P(\psi) \) is then used for construction of point estimates and test statistics such as the likelihood ratio statistic

\[
W = 2 [\ell_P(\hat{\psi}) - \ell_P(\psi)]
\]

for inference on \( \psi \), or the signed square root

\[
R = \text{sgn}(\hat{\psi} - \psi) \sqrt{W}
\]

when \( \psi \) is scalar. For stratified data, the usual asymptotic properties of \( \ell_P(\psi) \) are valid only when \( n = o(k) \), which is not very common in such settings (Sartori 2003).

3 Integrated likelihood for stratified censored data

The integrated likelihood function for \( \psi \) (Severini 2007), has the form

\[
\bar{L}(\psi) = \int_A L(\psi, \lambda) \pi(\lambda | \psi) d\lambda,
\]

where \( \pi(\lambda | \psi) \) is a nonnegative weight function for the nuisance parameter \( \lambda \in \Lambda \). It is not required for \( \pi(\lambda | \psi) \) to be a proper density, but its integral on the space \( A \) should have the same finite value given each \( \psi \). Severini (2007) provides suggestions for the proper choice of \( \pi(\lambda | \psi) \), so that the corresponding integrated likelihood has good frequentist properties.

To illustrate the idea behind the frequentist theory of integrated likelihood, let us consider the ideal situation where \( L(\theta) = L(\psi) L(\lambda) \), i.e., the likelihood factors and is then separable with respect to \( \theta \). In this case, integrated likelihoods can be completely independent of the selection of weight function, provided the latter does not depend on \( \psi \). This is because any choice of the weight function such that \( \pi(\lambda | \psi) = \pi(\lambda) \) leads the same integrated likelihood. Approximately, a similar situation can be obtained when parameters are orthogonal, i.e., the element \( i_\psi \lambda(\theta) \) of the Fisher information is null. Of course if separable likelihoods are encountered in practice, inference is based only on \( L(\psi) \) and we do not need to resort to pseudo likelihoods such as the integrated likelihood. In general, this case is not frequent and often the model parameters are not orthogonal. Moreover, the existence of an orthogonal parameterization is not guaranteed when \( \psi \) is not scalar.

Integrated likelihoods are based on a new nuisance parameter that is “unrelated” to \( \psi \), in the meaning proposed by Severini (2007) and explained below, so that the usual frequentist inferential properties of the resulting integrated likelihood are guaranteed. This new nuisance parameter, defined as \( \phi \equiv \phi(\psi, \lambda, \psi) \),
depends on the data only through \( \hat{\psi} \) and is obtained as an interest-respecting reparameterization of \( \theta = (\psi, \lambda) \). Assuming the two basic properties:

(a) \( \phi \) is strongly unrelated to \( \psi \), i.e., its constrained estimator \( \hat{\phi}_\psi \) is approximately constant as a function of \( \psi \), i.e., \( \hat{\phi}_\psi = \hat{\phi} + O(n^{-1/2})O(|\psi - \hat{\psi}|) \) for small deviation of \( \psi \) from \( \hat{\psi} \).

(b) the weight function for \( \psi \) does not depend on \( \psi \),

the integrated likelihood with respect to \( \pi(\phi), \phi \in \Phi \), is then given by

\[
\bar{L}(\psi) = \int_\phi \bar{L}(\psi, \phi)\pi(\phi)d\phi, \tag{6}
\]

where \( \bar{L}(\psi, \phi) \) is the likelihood reparameterized in \( (\psi, \phi) \). This integrated likelihood is then approximately score-unbiased to order \( O(n^{-1}) \), as opposed to the profile likelihood which has bias of order \( O(1) \).

The two major steps to compute the integrated likelihood in (6) consist of finding the parameter \( \phi \) and an opportune weight function \( \pi(\phi) \) so that properties (a) and (b) are fulfilled. It has been proved by Severini (2007) that property (a) is verified when \( \phi \equiv \phi(\psi, \lambda; \psi) \) is the solution to the equation

\[
E\{\ell_\lambda(\psi, \lambda); \hat{\psi}, \phi\} \equiv E\{\ell_\lambda(\psi, \lambda); \psi_0, \lambda_0\} \big|_{(\psi_0, \lambda_0) = (\hat{\psi}, \phi)} = 0, \tag{7}
\]

where \( (\psi, \lambda, \hat{\psi}) \) are considered as fixed values, \( \ell_\lambda(\cdot) \) denotes the partial derivative of the log likelihood function with respect to \( \lambda \), and \( E\{\cdot; \psi_0, \lambda_0\} \) denotes the expected value with respect to the distribution of the model random variables, with parameters equal to \( (\psi_0, \lambda_0) \). The solution \( \phi \) has been defined as the Zero-Score-Expectation (ZSE) parameter, since it recalls the likelihood property of score-unbiasedness.

When dealing with stratified data, under the assumptions previously made, it is sufficient to solve \( n \) independent equations

\[
E\{\ell_{\lambda_i}(\psi, \lambda_i); \hat{\psi}, \phi_i\} \equiv E\{\ell_{\lambda_i}(\psi, \lambda_i); \psi_0, \lambda_{i0}\} \big|_{(\psi_0, \lambda_{i0}) = (\hat{\psi}, \phi_i)} = 0, \tag{8}
\]

where \( \ell_{\lambda_i}(\psi, \lambda_i) \) are the \( n \) independent score functions for the nuisance parameters and the solutions \( \phi_i \) are the elements of the ZSE parameter \( \phi = (\phi_1, \ldots, \phi_n) \). Note that each equation and the corresponding solution \( \phi_i \) depend only on the parameter \( \lambda_i \).

It has been shown that for any arbitrary weight function fulfilling property (b), inferential results from integrated likelihoods are approximately unchanged. Thus, any choice of \( \pi(\phi) \) would be appropriate, and in practice it has been suggested to use the uniform function \( \pi(\phi) \propto 1 \). For a more general discussion about on the choice of the weight function see, e.g., Severini (2010).

Finally, inference based on the integrated log likelihood \( \bar{\ell}(\psi) = \log \bar{L}(\psi) \) can be performed by means of, e.g., the likelihood ratio statistics \( W = 2[\bar{\ell}(\bar{\psi}) - \bar{\ell}(\psi)] \), or, when \( \psi \) is scalar, its signed square root \( \bar{R} = \text{sgn}(\bar{\psi} - \psi)\sqrt{W} \) (Severini 2010), where \( \bar{\psi} \) is the maximum integrated likelihood estimate.
3.1 Integrated likelihood for stratified censored data

Under model (1), recall from Section 2 that the likelihood function for \((\psi, \lambda)\) is

\[
L(\psi, \lambda) = \prod_{i=1}^{n} L_i(\psi, \lambda_i) = \prod_{i=1}^{n} \left[ \prod_{j=1}^{k} h_{ij}(t_{ij}; \psi, \lambda_i) e^{C_{ij}(t_{ij}; \psi, \lambda_i)} \right],
\]

with \(L_i(\psi, \lambda_i) = \exp \{ \ell_i(\psi, \lambda_i) \} \).

In order to obtain the integrated likelihood given in (6), we need the ZSE parameter \(\phi\), which is found as a solution to equations (8), and the weight function \(\pi(\phi)\). In our setting, it is reasonable to choose a weight function with independent components of the form \(\pi(\phi) = \pi(\phi_1) \cdots \pi(\phi_n)\), with \(\phi_i \in \Phi\). The resulting integrated likelihood is then the product of \(n\) independent integrals

\[
\tilde{L}(\psi) = \prod_{i=1}^{n} \int_{\Phi} \tilde{L}_i(\psi, \phi_i) \pi(\phi_i) d\phi_i,
\]

where \(\tilde{L}(\psi, \phi) = \prod_i \tilde{L}_i(\psi, \phi_i)\) and \(\tilde{L}_i(\psi, \phi_i)\) is the likelihood contribution of the \(i\)th stratum reparameterized in \((\psi, \phi_i)\).

In the following, the procedure to find the ZSE parameter \(\phi = (\phi_1, \ldots, \phi_n)\) is presented for right-censored data, first, under type I censoring, and then assuming random censoring. Complete data are presented as a special case when all \(\delta_{ij} = 1\).

Let us define the vector of independent variables \(\Delta_i = (\Delta_{i1}, \ldots, \Delta_{ik})\). Assume without loss of generality that the random censoring times are equally distributed within each stratum, i.e., \(C_{i1} = \ldots = C_{ik} = C_i\).

(i) Type I censoring. The \(C_i\) can be considered as random variables with probability mass function \(Pr(C_i = c_i) = 1\). The fixed censoring times are known in advance for all subjects, and are equal for all observations within stratum \(i\), i.e., \(c_{i1} = \ldots = c_{ik} = c_i\) for \(i = 1, \ldots, n\). Consequently, the ZSE parameter is found as a solution to the equations

\[
E_{T_i, \Delta_i | C_i = c_i} \left[ (\lambda_i(\psi, \lambda_i); \psi_0, \lambda_0) \mid (\psi_0, \lambda_0) = (\hat{\psi}, \hat{\lambda}_i) = 0, \quad i = 1, \ldots, n, \right.
\]

with the expected values taken with respect to the conditional distribution of \((T_i, \Delta_i) | C_i = c_i\).

Computations shown in the Appendix lead to the explicit equations

\[
\sum_{j=1}^{k} \int_0^{c_i} \eta_{ij}(t; \psi, \lambda_i) p_{ij}(t; \psi_0, \lambda_0) dt - H_{ij}(c_i; \psi, \lambda_i) S_{ij}(c_i; \psi_0, \lambda_0) = 0, \quad (9)
\]

with \(\eta_{ij}(t; \psi, \lambda_i) = \frac{\partial}{\partial \psi} \log p_{ij}(t; \psi, \lambda_i)\), and \(H_{ij}(t; \psi, \lambda_i) = \frac{\partial}{\partial \lambda_i} \log S_{ij}(t; \psi, \lambda_i)\), for \(i = 1, \ldots, n\) and \(j = 1, \ldots, k\). The parameters \(\phi_i\) are the solutions to these equations after setting \((\psi_0, \lambda_0) = (\hat{\psi}, \phi_i)\).

If data are complete, \(\delta_{ij} = 1\) for all subjects and the equations reduce to

\[
\sum_{j=1}^{k} \int_0^{\infty} [\eta_{ij}(t; \psi, \lambda_i) - H_{ij}(t; \psi, \lambda_i)] p_{ij}(t; \psi_0, \lambda_0) dt = 0. \quad (10)
\]
Random censoring. The expectations involved are taken with respect to the marginal variable \((T_i, \Delta_i)\). Since noninformative censoring has been assumed and the \(c_{ij}\) are sufficient statistics for the parameter of the censoring distribution, it is convenient to write the expected value as \(E_{T, \Delta}(\cdot) = E_C [E_{T, \Delta}(\cdot | C)|\). We then obtain the ZSE equations as

\[
E_{T, \Delta_i} [\ell_{\lambda_i}(\psi, \lambda_i); \psi_0, \lambda_0] |_{(\psi_0, \lambda_0)=(\hat{\psi}, \hat{\phi})} = \int_0^\infty E_{T, \Delta_i | C_i=c} [\ell_{\lambda_i}(\psi, \lambda_i); \psi_0, \lambda_0] |_{(\psi_0, \lambda_0)=(\hat{\psi}, \hat{\phi})} g_i(c) \, dc, \quad i = 1, \ldots, n,
\]

where the conditional expectations given \(C_i = c_i\) are obtained from (9). The expected values in (11) are then set equal to zero to find \(\phi_i\) for \(i = 1, \ldots, n\).

4 Weibull model for stratified survival data

We illustrate the inferential procedure based on integrated likelihood for right-censored time-to-event data from a Weibull model. This model is of particular interest also because its logarithmic transformation leads to a parametric accelerated failure time model, frequently used in many areas of application.

Let \(T_{ij}\), \(i = 1, \ldots, n\) and \(j = 1, \ldots, k\), be independent failure times from Weibull distributions with probability density functions of the form

\[
p_i(t_{ij}) = \lambda_i \psi \lambda_i \cdot t_{ij}^{\psi-1} \exp\{-\lambda_i \cdot t_{ij}\},
\]

for \(t_{ij} \geq 0\), with shape parameter \(\psi > 0\) as the parameter of interest and nuisance scale parameters \(\lambda_i > 0\) for \(i = 1, \ldots, n\). Assume \(T_{i1}, \ldots, T_{ik}\) are i.i.d. with common scale parameter \(\lambda_i\).

Let us define the quantities \(\delta_i = \sum_{j=1}^k \delta_{ij}\), that is the number of observed events in the \(i\)th stratum, \(\delta = \sum_{i=1}^n \delta_i\), which gives the total number of observed events, and \(t_{i,\psi} = \sum_{j=1}^k t_{ij}^{\psi}\). Then, the \(i\)th contribution to the likelihood function has the form

\[
L_i^i(\psi, \lambda_i) = \psi^\delta \cdot \lambda_i^{\psi \delta_i} (\prod_j \delta_{ij}^{\psi-1}) \exp\{-\lambda_i \cdot t_{i,\psi}\}.
\]

If all the failure times are observed, we have \(\delta_{ij} = 1\) for all \(i = 1, \ldots, n\) and \(j = 1, \ldots, k\), and thus it is sufficient to replace \(\delta_i = k\) for all \(i\) and \(\delta = nk\) in equation (12). The maximum likelihood estimate \(\hat{\psi}\) is obtained as the maximum of the profile log likelihood function

\[
\ell_P(\psi) = \delta \cdot (\log \psi - 1) + (\psi - 1) \sum_i \sum_j \delta_{ij} \log t_{ij} + \sum_i \delta_i [\log \delta_i - \log t_{i,\psi}],
\]

(13)
4.1 The integrated likelihood

The integrated likelihood is constructed as

$$\bar{L}(\psi) = \prod_i \int_\phi \tilde{L}_i(\psi, \phi_i) \pi(\phi_i) d\phi_i,$$

where the $i$th stratum contribution, $i = 1, \ldots, n$, is

$$\tilde{L}_i(\psi, \phi_i) = \psi^{\delta_i} \left[ \lambda_i(\phi_i) \right]^{\psi \delta_i} \exp \left\{ -t_{ij} \left[ \lambda_i(\phi_i) \right]^\psi \right\} \prod_j t_{ij}^{\delta_j(\psi-1)}. \quad (14)$$

Each contribution $\tilde{L}_i(\psi, \phi_i)$ is obtained by reparameterizing equation (12) in $(\psi, \phi_i)$, i.e., writing $\lambda_i$ as a function of the ZSE parameter $\phi_i$. A natural choice for the weight function is $\pi(\phi_i) = 1$ for $i = 1, \ldots, n$.

In order to compute the integrated likelihood, it is necessary to find the ZSE parameter $\phi_i = (\phi_1, \ldots, \phi_n)$ so that the optimal inferential properties are guaranteed. For the Weibull model, this is equivalent to find the parameters $\phi_i$ as solutions of the $n$ independent equations

$$E\{t_{ij}(\psi, \lambda_i); \hat{\psi}, \phi_i\} - k \psi \lambda_i^{\psi-1} E\{T_{ij}^\psi; \hat{\psi}, \phi_i\} = 0, \quad (15)$$

where here we have defined $E\{\cdot; \hat{\psi}, \phi_i\} \equiv E\{\cdot; \hat{\psi}, \lambda_0\} \mid_{(\psi_0, \lambda_0) = (\hat{\psi}, \phi_i)}$. These equations are obtained considering that $T_{i1}, \ldots, T_{ik}$ are i.i.d., and the score functions for the nuisance parameter are $\ell_{\lambda_i}(\psi, \lambda_i) = (\delta_i \psi / \lambda_i) - \psi \lambda_i^{\psi-1} t_{ij} \psi$, for $i = 1, \ldots, n$, and depend on the data only through the statistic $t_{ij} \psi = \sum_{j=1}^k t_{ij}^\psi$.

Solving equations (15) for $\phi_i$, for $i = 1, \ldots, n$, does not always yield solutions in closed form. However, in order to compute the integrated likelihood, it is sufficient to find the explicit relation between the original nuisance parameter $\lambda_i$ and $\phi_i$. Therefore, from equation (15), simple algebra provides the nuisance parameter $\lambda_i$ as a function of $\phi_i$, i.e.,

$$\lambda_i = \lambda_i(\phi_i) = \left[ \frac{E\{\Delta_{ij}; \hat{\psi}, \phi_i\}}{E\{T_{ij}^\psi; \hat{\psi}, \phi_i\}} \right]^\frac{1}{\psi}, \quad (16)$$

which allows us to specify completely the integrand (14). The main integral is a product of $n$ one-dimensional integrals, and each of them can be solved independently by standard numerical methods.

The expected values in (16) are computed in different ways depending on the censoring mechanism. In the following the results for both type I and random censoring are reported, with details given in the Appendix.

4.2 Weibull model under type I censoring

Under fixed censoring, the expected values in (16) are taken with respect to the conditional variables $\Delta_{ij} | C_i = c_i$ and $T_{ij} | C_i = c_i$, i.e., they are computed as $E_{\Delta_{ij} | C_i = c_i}\{\Delta_{ij}; \hat{\psi}, \phi_i\}$ and $E_{T_{ij} | C_i = c_i}\{T_{ij}^\psi; \hat{\psi}, \phi_i\}$.
As shown in the Appendix, the final equations of the ZSE parameters are
\[
\frac{k_{\psi}}{\lambda_i} \left\{ 1 - e^{-\left(\phi_i, c_i\right)^{\hat{\psi}}} \left[ 1 + (\lambda_i c_i)^{\psi} \right] - \left( \frac{\lambda_i}{\phi_i} \right)^{\psi} a(\hat{\phi}_i, \hat{\psi}, \hat{\psi}) \right\} = 0
\]
for \( i = 1, \ldots, n \), where \( a(\phi, \psi, \psi) = \Gamma_{I} \left( \psi/\hat{\psi} + 1, (\phi, c)^{\hat{\psi}} \right) \) and \( \Gamma_{I} \left( \cdot, \cdot \right) \) is the incomplete gamma function. From the above equations, the nuisance parameter \( \lambda_i \) can be written as a function of \( \phi_i \) as follows
\[
\lambda_i(\phi_i) = \left[ \frac{E_{\Delta_{ij} \mid C_i = c_i} \{ \Delta_{ij}; \hat{\psi}, \hat{\phi}_i \}}{E_{T_{ij} \mid C_i = c_i} \{ T_{ij}^{\psi}; \hat{\psi}, \hat{\phi}_i \}} \right]^{1/\psi} = \phi_i \left[ 1 - e^{(\phi_i, c_i)^{\hat{\psi}}} \right] \left[ \frac{1}{a(\hat{\phi}_i, \hat{\psi}, \hat{\psi}) + (\phi_i c_i)^{\psi} e^{(\phi_i, c_i)^{\psi}}} \right]^{1/\psi}.
\]

4.3 Weibull model under random censoring

For simplicity, let us assume that \( C_{ij} \) for \( i = 1, \ldots, n \) and \( j = 1, \ldots, k \), are i.i.d and exponentially distributed, i.e., \( C_{ij} \sim \text{Exp}(\nu) \) with density \( g(c) = \nu e^{-\nu c} \) and survival \( G(c) = e^{-\nu c} \). However, less restrictive assumptions are also possible, e.g., \( C_{ij} \sim \text{Exp}(\nu_j) \) for \( j = 1, \ldots, k \), with different parameters \( \nu_j \) across strata.

Under random censoring, the expected values in (16) are taken with respect to the unconditional variable \( \Delta_{ij} \) and \( T_{ij} \). However, they can be computed by integrating the conditional expectations given \( C_{ij} = c \) with respect to \( c \). Namely, it can be shown that
\[
E_{C_{ij}} \left\{ E_{\Delta_{ij} \mid C_i = c_i} \{ \Delta_{ij}; \nu \} \right\} = 1 - \int_{0}^{\infty} \nu e^{-(\phi, c)^{\hat{\psi}}} dc,
\]
and
\[
E_{C_{ij}} \left\{ E_{T_{ij} \mid C_i = c_i} \{ T_{ij}^{\psi}; \nu \} \right\} = \int_{0}^{\infty} t^{\psi} \left( \psi t^{\hat{\psi} - 1} \hat{\phi} + \nu \right) e^{-(\phi, t)^{\hat{\psi}}} dt,
\]
where the integrals involved are not an issue and can be solved by standard numerical approximations. More details are given in the Appendix.

In order to compute the integrated likelihood for \( \psi \), the original nuisance parameter \( \lambda_i \) can be easily written as a function of the ZSE parameter \( \phi_i \) as follows
\[
\lambda_i(\phi_i) = \left[ \frac{E_{\Delta_{ij} \mid C_i = c_i} \{ \Delta_{ij}; \hat{\psi}, \hat{\phi}_i \}}{E_{T_{ij} \mid C_i = c_i} \{ T_{ij}^{\psi}; \hat{\psi}, \hat{\phi}_i \}} \right]^{1/\psi},
\]
where the maximum likelihood estimate \( \hat{\nu} \) is employed as a plug-in estimate for \( \nu \).

5 Simulation studies

Monte Carlo simulation studies with 5000 trials were conducted to investigate the performance of integrated likelihood methods for inference on the parameter of interest \( \psi \). Results were also compared with those obtained from the profile likelihood. We simulated stratified data from the Weibull model presented in Section 4 under no censoring (complete data), type I censoring and random censoring.
To achieve good inferential properties of integrated likelihoods, proper weight functions of the ZSE nuisance parameter should not depend on the parameter of interest. To investigate also this issue in simulation studies, we studied an integrated likelihood with constant weights \( \pi(\phi_1) = \ldots, \pi(\phi_n) = 1 \), denoted as \( \bar{\ell}(\psi) \), and an integrated likelihood with improper \( \psi \)-dependent weights, denoted as \( \bar{\ell}_D(\psi) \). For simplicity, the latter weights are chosen so that the integrated likelihood has a closed form. This is possible when, in order to solve the integral, we set \( z = t_{1, \psi} \lambda_i(\phi_i)^{\psi} \) and \( dz/d\phi_i = \lambda_i(\phi_i)^{\psi} \). The simulation studies investigated the coverage probabilities of confidence intervals of level 0.95 based on the signed likelihood ratio statistic. This statistic was computed for the profile log likelihood (\( R \)), for the integrated log likelihood with constant weights for the ZSE parameters (\( \bar{R} \)), and for the integrated log likelihood with \( \psi \)-dependent weights (\( \bar{R}_D \)). The integrated signed likelihood ratio statistic, and the standard signed likelihood ratio statistic, are considered asymptotically standard normal, and the approximation to its distribution is often more accurate for the former.

We considered \( n = 5, 20, 100, 250 \) for the number of strata (equal to the dimension of the nuisance parameter), and different within-stratum sample sizes, \( k = 10, 30, 60 \). For censored data, we also assumed different censoring probabilities \( P_c = 0.2, 0.4, 0.6 \). Table 1 shows the results from stratified complete data sampled from Weibull distributions with common shape parameter \( \psi = 1.5 \) and different scale parameter \( \lambda_i = 0.2i \) for \( i = 1, \ldots, n \). The empirical bias of \( \psi \) is close to zero for almost all scenarios, while the maximum likelihood estimates for \( \psi \) can be severely biased, in particular when the number of observations within strata is low (\( k = 10 \)), and the maximum likelihood estimate bias remains constant when \( n \) increases, as known in the literature (Sartori 2003).

Simulated data under type I censoring were sampled from Weibull distributions with the same parameters as for the complete data. The fixed censoring times \( c_i \)
were assumed to be equal within each stratum, and were obtained as solutions when setting the survival $G_i(c_i)$ equal to the desired censoring probability. Results from Tables 2 and 3 show a very good performance of integrated likelihood for all different $k$ and $n$ and for all censoring probabilities. The empirical coverage probabilities for $\hat{R}$ are very close to the nominal values, in contrast to the empirical coverages for $R$, which perform very poorly. In particular, the latter get worse when $n$ increases, for decreasing $k$, and for lower censoring probabilities, producing in some cases critical inferential results which are substantially wrong (e.g., for $P_c = 0.2, 0.4$, $n = 250$ and $k = 10$). For the profile likelihood, empirical errors on the tails of the distribution are very asymmetric and the asymmetry worsens when $n$ increases and $k$ decreases. In contrast, the integrated likelihood provides very symmetric empirical errors in all scenarios. The empirical bias for $\hat{\psi}$ is systematically lower than the bias for $\tilde{\psi}$ and reaches very low values when $k$ and $n$ increase (e.g., the bias $< 0.001$ for $n = 100, 250$ and $k = 30, 60$). We note a substantial reduction of the bias for $\tilde{\psi}$ with respect to $\hat{\psi}$ for small samples, independently of the value of $n$. Empirical standard errors are approximately equal. Tables 2 and 3 report also numerical results from the integrated likelihood with improper $-\psi$-dependent weights, as defined above. This counter-example shows very poor performance of the integrated likelihood if the weight function on the nuisance parameter depends on $\psi$, since the property of orthogonality is violated.

Stratified data under random censoring were simulated again from Weibull distributions with shape parameter $\psi = 1.5$. The scale parameters $\lambda_i$ for $i = 1, \ldots, n$ were sampled from a Normal distribution with mean 3 and variance 0.5^2. Then, it was assumed that $C_{ij} \sim \text{Exp}(\nu)$; given $(\lambda_1, \ldots, \lambda_n)$ and a certain probability of censoring $P_c$, the parameter $\nu$ was found as a solution to the equation

$$\frac{1}{n} \sum_{i=1}^{n} \Pr(\tilde{T}_{ij} > C_{ij}) = \frac{1}{n} \sum_{i=1}^{n} E\{\Delta_{ij}; \tilde{\psi}, \lambda_i, \nu\} = P_c.$$

Under random censoring, simulated results based on the integrated likelihood are even better than under type I censoring, as shown in Tables 4 and 5. Empirical coverages for $\tilde{R}$ are very near to the nominal levels, whereas empirical coverages for $R$ are substantially wrong for most cases. They perform worse when $n$ increases, $k$ decreases and for lower censoring probabilities, and they fail completely for $n = 100, 250$ and $k = 10, 30$. Numerical results about the estimates for $\psi$ are very similar to those under type I censoring.

Finally, we compare the estimated standard errors for $\hat{\psi}$ and $\tilde{\psi}$ given in Tables 3 and 5, respectively. Standard errors obtained for the maximum likelihood estimator are systematically biased downward, especially for lower $k$, and high censoring probability (0.6), independently of $n$. This may be the reason why we have the counterintuitive fact that empirical coverages based on profile likelihood improves when the censoring probability increases. Standard errors obtained from integrated likelihood estimation are instead always very accurate.

The robustness of the proposed inferential approach to misspecification of the censoring distribution was investigated with additional simulation studies. Censoring times were generated under a uniform distribution, whereas an incorrect exponential model was assumed. We found that in general the results based on integrated likelihoods are very robust to the assumed misspecification of the censoring distribution (see Tables 1 and 2 in Supplementary material).
Table 2 Type I-censored data: Empirical percentage coverage probabilities of two-sided 95% confidence intervals based on the profile ($\hat{R}$) and integrated log likelihoods ($\bar{R}$: uniform weights; $\bar{R}_D$: $\psi$-dependent weights), for different censoring probabilities. Lower and upper empirical non-coverage probabilities are given in brackets.

<table>
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<tr>
<th>$P_c$</th>
<th>$n$</th>
<th>$k$</th>
<th>$\hat{R}$</th>
<th>$\bar{R}$</th>
<th>$\bar{R}_D$</th>
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</tr>
<tr>
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<td></td>
</tr>
<tr>
<td></td>
<td>60</td>
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<td>94.7 (3.4, 2.0)</td>
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<tr>
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<tr>
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<td>94.8 (2.9, 2.3)</td>
<td>83.9 (15.9, 0.1)</td>
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</tr>
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</table>

6 The accelerated failure time regression model for real data from HIV-infected patients

In this section we provide an example of how the integrated likelihood method can be applied to regression models for stratified survival data. Let us consider data from a clinical trial comparing two treatments (group 2 vs group 1) for Mycobacterium avium complex, which is a frequent disease in late-stage HIV-infected people. The data were illustrated in Carlin (1999) for fitting a stratified parametric Weibull model, and part of the trial was reported in Cohn et al. (1999). A total of 69 patients coming from 11 different clinical centers were enrolled in
Table 3  Type I-censored data: Estimates of the parameter of interest $\psi$ obtained from profile and integrated likelihoods, for different censoring probabilities. Bias, simulation-based empirical standard errors (s.e.), and ratios between the average of estimated standard errors (e.s.e.) and s.e. are provided.

<table>
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<tr>
<th>$P_c$</th>
<th>n</th>
<th>k</th>
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<th>$\hat{\psi}$ s.e./s.e.</th>
<th>Bias s.e.</th>
<th>$\hat{\psi}$ s.e.</th>
<th>$\hat{\psi}$ s.e./s.e.</th>
<th>Bias s.e.</th>
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<td>0.029</td>
<td>0.995</td>
<td>-0.018</td>
<td>0.028</td>
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<td>0.051</td>
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<td>0.989</td>
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<td>0.800</td>
<td>-0.001</td>
<td>0.026</td>
<td>1.009</td>
<td>-0.034</td>
<td>0.024</td>
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<td>0.795</td>
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<td>1.001</td>
<td>-0.018</td>
<td>0.018</td>
<td>1.016</td>
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</table>

The trial, and between them, 5 patients died in the treatment group 1 and 13 in the group 2. The endpoint of interest was time to death. The interesting aspect of these data is that many centers have enrolled a relatively small number of patients. Moreover, a high proportion of randomly censored patients was observed (74%), no events were observed in 3 centers and few deaths (1 to 4) were observed in each of the remaining centers.

For such data, the censoring mechanism is assumed to be random, the different clinical centers represent the strata and the type of treatment is the covariate of interest, $x_{ij}$. Consider a regression model with hazard function $h_i(t; x_{ij}) =$
Table 4 Randomly-censored data: Empirical percentage coverage probabilities of two-sided 95% confidence intervals based on the profile (\(R\)) and integrated (\(\overline{R}\)) likelihoods, for different censoring probabilities. Lower and upper empirical non-coverage probabilities are given in brackets.

<table>
<thead>
<tr>
<th>(P_c)</th>
<th>(n)</th>
<th>(k)</th>
<th>(R)</th>
<th>(R)</th>
</tr>
</thead>
<tbody>
<tr>
<td>10</td>
<td>90.1 (0.7, 9.2)</td>
<td>94.6 (2.5, 2.9)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>30</td>
<td>93.9 (0.8, 5.3)</td>
<td>95.5 (2.0, 2.5)</td>
<td></td>
</tr>
<tr>
<td>60</td>
<td>93.7 (1.6, 4.7)</td>
<td>94.5 (2.7, 2.8)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>10</td>
<td>78.1 (0.1, 21.7)</td>
<td>94.9 (2.6, 2.5)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>20</td>
<td>30</td>
<td>90.0 (0.6, 9.4)</td>
<td>95.1 (2.6, 2.3)</td>
<td></td>
</tr>
<tr>
<td>60</td>
<td>92.2 (0.9, 6.9)</td>
<td>95.1 (2.4, 2.5)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>10</td>
<td>27.5 (0.0, 72.5)</td>
<td>95.3 (2.4, 2.4)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>100</td>
<td>30</td>
<td>71.1 (0.0, 28.9)</td>
<td>95.0 (2.7, 2.3)</td>
<td></td>
</tr>
<tr>
<td>60</td>
<td>83.6 (0.1, 16.3)</td>
<td>94.7 (2.6, 2.7)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>10</td>
<td>2.4 (0.0, 97.6)</td>
<td>95.0 (2.8, 2.2)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>250</td>
<td>30</td>
<td>40.1 (0.0, 59.9)</td>
<td>94.8 (3.0, 2.3)</td>
<td></td>
</tr>
<tr>
<td>60</td>
<td>65.5 (0.0, 34.5)</td>
<td>95.2 (2.6, 2.2)</td>
<td></td>
<td></td>
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</table>

\(h_0(t) \xi_i e^{\beta x_{ij}}\), where \(h_0(t)\) is the common baseline hazard, \(\xi_i\) for \(i = 1, \ldots, n\) are the stratum-specific effects and \(x_{ij}\) is the covariate of the \(j\)th individual in stratum \(i\). This is a proportional hazards model with stratum-specific baseline hazards \(h_{0i}(t) = h_0(t)\xi_i\). Let the survival times to death be independent variables such that \(\tilde{T}_{ij} \sim \text{Weibull}(\eta_{ij}, \psi_1)\). Then, in order to have a Weibull regression model, the \(i\)th stratum’s scale parameter is set to be \(\psi  = \psi_1 \psi_2\). If we use the parameterization \(\xi_i = e^{-\psi_1 \alpha_i}\) and \(\beta = -\psi_1 \psi_2\), the hazard for center \(i\) can be written as

\[
h_i(t; x_{ij}) = h_0(t) \xi_i e^{\beta x_{ij}} = \psi_1 t^{-\psi_1^{-1}} e^{-\psi_1 (\alpha_i + \psi_2 x_{ij})},
\]
Table 5 Randomly-censored data: Estimates of the parameter of interest $\psi$ obtained from profile and integrated likelihoods, for different censoring probabilities. Bias, simulation-based empirical standard errors (s.e.), and ratios between the average of estimated standard errors (e.s.e.) and the s.e. are provided.

<table>
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<th>$P_c$</th>
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<th>$k$</th>
<th>Bias</th>
<th>s.e.</th>
<th>e.s.e./s.e.</th>
<th>Bias</th>
<th>s.e.</th>
<th>e.s.e./s.e.</th>
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<td>0.896</td>
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<td>0.205</td>
<td>0.980</td>
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<td>0.022</td>
<td>0.078</td>
<td>0.955</td>
<td>0.005</td>
<td>0.077</td>
<td>0.984</td>
<td></td>
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<tr>
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<td>0.118</td>
<td>0.108</td>
<td>0.907</td>
<td>0.004</td>
<td>0.099</td>
<td>0.992</td>
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<tr>
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<td>0.055</td>
<td>0.961</td>
<td>0.001</td>
<td>0.054</td>
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<td>0.919</td>
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with baseline hazard $h_0(t) = \psi_1 t^{\psi_1 - 1}$. Our aim is to make inference for the parameter of interest $\psi = (\psi_1, \psi_2)$, i.e. for the treatment effect $\beta$, while treating the vector of stratum-specific effects ($\alpha_1, \ldots, \alpha_n$) as nuisance parameter.

For ease of interpretation, the Weibull regression model can also be transformed to an accelerated failure time model, by considering the log-transformation $U_{ij} = \text{log}T_{ij}$. In this case we have the linear model $U_{ij} = \alpha_i + \psi_2 x_{ij} + \sigma \epsilon_{ij}$, where $\epsilon_{ij}$ has an extreme value distribution and $\sigma = 1/\psi_1$. This model leads to proportional cumulative hazards on the time scale, i.e., $H_1(t) = H_2(t/c)$ for any constant $c$. 
Standard profile likelihood methods lead to the maximum likelihood estimates \( \hat{\psi}_1 = 1.149 \) (s.e. 0.219) and \( \hat{\psi}_2 = -1.012 \) (s.e. 0.484). For the invariance property, we obtain that the relative risk is estimated to be \( e^{\hat{\beta}} = 3.198 \), indicating a higher mortality rate for patients under treatment 2. The likelihood ratio statistic was used for testing the null hypothesis \( \psi_2 = 0 \) and the treatment effect was found to be significant at the 0.05 level (\( W(\psi_2 = 0) = 4.896, \ p = 0.027 \)). The likelihood ratio test for \( \psi_1 = 1 \) provided a nonsignificant result and this suggests that a simpler exponential regression model could be assumed for fitting our HIV data. When we assumed \( \psi_1 = 1 \), testing for the null effect of \( \psi_2 \) gave very similar conclusions. The likelihood ratio-based confidence intervals for \( \psi_1 \) and \( \psi_2 \) are respectively, (0.742, 1.669), and (-2.310, -0.111).

If inference is based on integrated likelihood, the ZSE for the Weibull regression model can be computed directly from Section 4, under the assumption of random censoring, by using the parameterization

\[
\eta_{ij} = e^{-(\alpha_i + \psi_2 x_{ij})}.
\]

The scale parameters, as well the ZSE, depend also on the index \( j \) because of the presence of covariates. Then \( \eta_{ij} \) and \( \phi_{ij} \) play here the same role as, respectively, the parameters \( \lambda_i \) and \( \phi_i \) in Section 4. Using the invariance property of integrated likelihoods with respect to reparameterizations of the ZSE parameter, the new ZSE parameter, \( \omega_i \), is obtained from the relation \( \phi_{ij} = e^{-(\omega_i + \psi_2 x_{ij})} \). Details are given in the Appendix.

The integrated likelihood is then

\[
\hat{L}(\psi_1, \psi_2) = \prod_{i=1}^{n} \int_{-\infty}^{+\infty} \tilde{L}^i(\psi_1, \psi_2, \omega_i) \pi(\omega_i) d\omega_i,
\]

where the integrand has the form

\[
\tilde{L}^i(\psi_1, \psi_2, \omega_i) = \psi_1^{\delta_i} A_i \exp\{-\psi_2 \delta_i \alpha_i(\omega_i) - \psi_1 \psi_2 X_i - B_i e^{-\psi_1 \alpha_i(\omega_i)}\}
\]

with

\[
A_i = \prod_{j} i_{ij}^{(\psi_1 - 1) \delta_i}, \quad B_i = \sum_{j} i_{ij}^{\psi_1} e^{-\psi_1 \psi_2 x_{ij}}, \quad X_i = \sum_{j} x_{ij} \delta_{ij},
\]

and with \( \alpha_i(\omega_i) \) given in (29) in the Appendix.

The integrated likelihood, obtained using \( \pi(\omega_i) = 1 \), leads to the estimates \( \hat{\psi}_1 = 1.037 \) (s.e. 0.207) and \( \hat{\psi}_2 = -1.017 \) (s.e. 0.536). Using the property of parameterization invariance of integrated likelihoods, the relative risk was estimated to be \( e^{\hat{\beta}} = 2.869 \). The hazard ratio and the estimated \( \psi_1 \) from the integrated likelihood are lower than those from the profile likelihood. Tests and confidence intervals can be computed using a \( \chi^2 \) approximation for the distribution of the integrated likelihood ratio statistics, e.g. for \( \psi_1 \), \( \bar{W}(\psi_1) = 2[\tilde{L}(\hat{\psi}_1, \hat{\psi}_2) - \tilde{L}(\hat{\psi}_1, \hat{\psi}_2, \hat{\omega}_1)] \), where \( \hat{\omega}_1 \) is the constrained estimate of \( \psi_2 \) for fixed \( \psi_1 \) obtained from \( \tilde{L}(\hat{\psi}_1, \hat{\psi}_2) \). The test for the null hypothesis \( \psi_2 = 0 \) showed that the significance of the treatment effect is borderline at the 0.05 level (\( \bar{W}(\psi_2 = 0) = 3.983, \ p = 0.046 \)). Thus, unlike the test based on profile likelihood, we conclude here that there is weaker evidence against the null additional effect of treatment 2 with respect to treatment 1. The result of testing the null hypothesis \( \psi_1 = 1 \) was the same as for the profile
Fig. 1 Relative log likelihood for $\psi_1$ and $\psi_2$ and corresponding confidence intervals (dotted lines), computed from the profile likelihood (solid lines) and the integrated likelihood (dashed lines).

The different results obtained under the two inferential methods are illustrated in Figure 1, where the relative log likelihoods, i.e. $-\frac{1}{2}W(\psi_k)$ and $-\frac{1}{2}W(\psi_k)$, $k = 1, 2$, are plotted. Point and interval estimates for the shape parameter $\psi_1$ under the integrated likelihood have lower values than those under the profile likelihood, however confidence intervals have very similar length. The estimate for $\psi_2$ is almost the same under the two inferential methods, whereas the confidence interval for $\psi_2$ computed with the integrated likelihood is slightly wider, as also shown in the right panel of Figure 1. Note that the contribution to the profile likelihood is null for the strata containing only censored observations ($\delta_i = 0$) with possible consequences on the inferential results, while this is not necessarily true for the integrated likelihood. These conflicting data results were also widely discussed in the literature (Cohn et al. 1999). It is reasonable to think that this problem may be due to lack of accuracy of the inferential approach in presence of stratified data, rather than the results of choosing between unstratified and stratified analysis (Carlin and Hodges 1999).

7 Discussion

Standard likelihood inference may be seriously biased when dealing with stratified data (McCullagh and Tibshirani 1990; Sartori 2003), especially if the number of strata is large. This problem happens because the profile score function does not provide an unbiased estimating equation, with bias generally increasing with the number of strata $n$, i.e. number of nuisance parameters. For inferential purposes integrated likelihoods are an appealing alternative since they have a score function with reduced bias and the same asymptotic properties as the modified profile likelihood (De Bin 2012; De Bin et al. 2014). The latter pseudo likelihood has been
studied for censored survival data only to a limited extent (Pierce and Bellio 2006), and it is not straightforward to compute in practice due to the complexity of the quantities involved. In contrast, integrated likelihoods have not been investigated for censored survival data. The results here show their benefits, especially for highly stratified survival data.

The simulation studies confirm the superiority of the integrated likelihood over the profile likelihood for stratified right-censored data when a Weibull model and noninformative independent censoring are assumed. The numerical results show that, as expected, inference based on profile likelihood is very inaccurate and provides serious under-coverages of confidence intervals, which lead to extremely high empirical type I errors. These problems are particularly emphasized when the number of strata \( n \) increases with respect to the within-stratum size \( k \). On the contrary, the integrated likelihood shows very good performance both in terms of accuracy of the corresponding estimates, and coverage probabilities of confidence intervals in all scenarios, and the results do not seem to be affected by increasing proportions of censoring in the data.

In this work we used the likelihood ratio statistic for constructing confidence intervals. This was motivated by their invariance properties. However, in the literature it has been shown that score, Wald and likelihood ratio statistics are still asymptotically equivalent, even in the extreme scenario provided by stratified data. Moreover, this equivalence is valid independently of the chosen likelihood method (profile, modified profile or integrated likelihood) (Sartori 2003; De Bin 2012; De Bin et al. 2014). This fact suggests that also for stratified survival data, the Wald and score statistics are expected to give improved accuracy in inference when they are based on a suitable integrated likelihood.

The integrated likelihood is, as the profile likelihood, invariant with respect to interest-preserving reparameterizations. Its computation relies often on numerical integration and therefore careful implementation is needed in order to obtain efficient code. Our implementation in the R framework (R Core Team 2013) made use of C subroutines to speed up computation in case of many strata. The code is available from the first author upon request.

Finally, it should be noted that with random censoring the integrated likelihood relies on the censoring distribution, which is needed for computing the ZSE parameter, while the profile likelihood is independent of such distribution. Even though we found that the integrated likelihood is fairly robust to misspecification of the censoring distribution, the use of a completely nonparametric censoring distribution in the construction of the integrated likelihood is certainly of interest and will be the subject of future research. Also applications of the integrated likelihood approach to more general settings, such as left-truncated data, informative censoring, and semiparametric models, could be worth considering.

Acknowledgements The second author acknowledges the financial support of the CARI-PARO Foundation Excellence - grant 2011/2012.

References

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A Appendix

A.1 Integrated likelihood in parametric stratified models: Type I censoring

In the following, it is explained how to find the ZSE parameter \( \phi = (\phi_1, \ldots, \phi_n) \) as a solution to the \( n \) independent equations

\[
E_{T_i, \Delta_i | C_i = c_i} \left[ \ell_{\lambda_i}(\psi, \lambda_i); \psi_0, \lambda_0 \right] | (\psi_0, \lambda_0) = (\hat{\psi}, \hat{\lambda}_i) = 0, \quad i = 1, \ldots, n,
\]

where the expected values are taken with respect to the conditional variables \((T_i, \Delta_i)|C_i = c_i\).

Let us consider the partial derivatives

\[
\ell_{\lambda_i}(\psi, \lambda_i) = \sum_j \ell_{\lambda_i}^j(\psi, \lambda_i) = \sum_j [\delta_{ij} \eta_j(t_{ij}; \psi, \lambda_i) - (1 - \delta_{ij}) H_{ij}(t; \psi, \lambda_i)].
\]

where \( \delta_{ij} \) is the \( j \)th likelihood contribution of the \( i \)th stratum, \( \eta_j(t; \psi, \lambda_i) = \frac{\partial}{\partial \lambda_i} \log p_{ij}(t; \psi, \lambda_i) \), and \( H_{ij}(t; \psi, \lambda_i) = \frac{\partial}{\partial \lambda_i} \log S_{ij}(t; \psi, \lambda_i) \), for \( i = 1, \ldots, n \) and \( j = 1, \ldots, k \). Since the pairs \((T_{i1}, \Delta_{i1}), \ldots, (T_{ik}, \Delta_{ik})\) are assumed to be independent, the equations can be evaluated as follows:

\[
E_{T_i, \Delta_i | C_i = c_i} \left[ \ell_{\lambda_i}(\psi, \lambda_i); \psi_0, \lambda_0 \right] = \sum_{j=1}^{k} E_{T_i, \Delta_i | C_i = c_i} \left[ \ell_{\lambda_i}^j(\psi, \lambda_i); \psi_0, \lambda_0 \right] = \sum_{j=1}^{k} \sum_{\delta_{ij} = 0}^{1} \int_{0}^{\infty} \ell_{\lambda_i}^j(\psi, \lambda_i) f_{T_i, \Delta_i | C_i = c_i}(t; \delta_{ij}; \psi_0, \lambda_0) dt,
\]

where the conditional densities \( f_{T_i, \Delta_i | C_i = c_i}(t) \) given in (2) are employed. For \( \delta_{ij} = 1 \), they are equal to \( p_{ij}(t) \) in the interval \( t \in [0, c_{ij}) \) and 0 elsewhere, while for \( \delta_{ij} = 0 \) they reduce to \( S_{ij}(t) \) in the point \( t = c_{ij} \) and 0 elsewhere. Therefore, computing the equation (20) leads to the final explicit equations

\[
\sum_{j=1}^{k} \int_{0}^{c_{ij}} \eta_j(t; \psi, \lambda_i) p_{ij}(t; \psi_0, \lambda_0) dt - H_{ij}(c_i; \psi, \lambda_i) S_{ij}(c_i; \psi_0, \lambda_0) = 0.
\]

The parameters \( \phi_i \) are the solutions to these equations after setting \((\psi_0, \lambda_0) = (\hat{\psi}, \hat{\lambda}_i)\).

A.2 Integrated likelihood in the Weibull model: Type I censoring

For the Weibull model, the ZSE is obtained from equation (15), and the expected values therein are computed as conditional expectations given \( C_i = c_i \), with respect to the density function

\[
f_{T_{ij} | C_i = c_i}(t_{ij}; \psi, \lambda_i) = p_{ij}(t_{ij}; \psi, \lambda_i) \Delta_i(t_{ij}) + S_i(c_i; \psi, \lambda_i) \Delta_i(t_{ij}).
\]

This function is equivalent to the density of the observed time \( T_{ij} = \min(T_{ij}, c_i) \). Therefore,

\[
E_{\Delta_i | C_i = c_i} \left\{ \Delta_{ij} ; \hat{\psi}, \hat{\lambda}_i \right\} = \mathrm{Pr}(T_{ij} < c_i; \psi_0, \lambda_0) | (\psi_0, \lambda_0) = (\hat{\psi}, \hat{\lambda}_i) = 1 - S(c_i; \hat{\psi}, \hat{\lambda}_i) = 1 - e^{-(\lambda_i/c_i)} \hat{\psi},
\]

\[
E_{T_{ij} | C_i = c_i} \left\{ T^\psi_{ij} ; \hat{\psi}, \hat{\lambda}_i \right\} = \int_{0}^{\infty} t^\psi f_{T_{ij} | C_i = c_i}(t; \hat{\psi}, \hat{\lambda}_i)dt
\]

\[
= \int_{0}^{c_i} u^\psi p_u(u; \hat{\psi}, \hat{\lambda}_i)du + c_i^\psi S_i(c_i; \hat{\psi}, \hat{\lambda}_i)
\]

\[
= \left( \frac{1}{\hat{\psi}^\psi} \right)^\psi \Gamma \left( \frac{\psi}{\psi} + 1 \right) (\hat{\lambda}_i/c_i)^{\psi} + c_i^\psi e^{-(\hat{\lambda}_i/c_i)} \hat{\psi}.
\]
where $\Gamma_I(s, x) = \int_0^x t^{s-1} e^{-t} dt$ is the incomplete gamma function.

The final equations of the ZSE are given as

$$
\frac{k\psi}{\lambda_i} \left\{ 1 - e^{-\left(\phi_i, c_i\right)^\psi} \right\} \left[ 1 + \left(\lambda_i c_i\right)^\psi \right] - \left(\frac{\lambda_i}{\phi_i}\right)^\psi a(\phi_i, \psi, \hat{\psi}) = 0
$$

for $i = 1, \ldots, n$, where $a(\phi_i, \psi, \hat{\psi}) = \Gamma_I \left( \frac{\psi}{\hat{\psi}} + 1, (\phi_i, c_i)^\psi \right)$. If we allow censoring times to be different within each stratum, the ZSE equation become

$$
\frac{\psi}{\lambda_i} \sum_j \left\{ 1 - e^{-\left(\phi_i, c_{ij}\right)^\psi} \right\} \left[ 1 + \left(\lambda_i c_{ij}\right)^\psi \right] - \left(\frac{\lambda_i}{\phi_i}\right)^\psi a(\phi_i, \psi, \hat{\psi}) = 0.
$$

Solving these equations for $\phi_i$, for $i = 1, \ldots, n$, does not yield solutions in closed form. However, in order to compute the integrated likelihood, it is sufficient to find the nuisance parameter $\lambda_i$ as a function of $\phi_i$ from the above equations, as follows

$$
\lambda_i(\phi_i) = \left[ \frac{E_{\Delta_{ij}|C_i=c_{ij}} \{ \Delta_{ij}; \hat{\psi}, \phi_i \}}{E_{T_{ij}|C_i=c_{ij}} \{ T_{ij}^\psi ; \hat{\psi}, \phi_i \}} \right]^{1/\psi}.
$$

Formulae for complete data may be obtained as a special case when $c_{ij} \rightarrow \infty$; then we have $E\{\Delta_{ij}; \hat{\psi}, \phi_i\} = 1$ and $E\{T_{ij}^\psi; \hat{\psi}, \phi_i\} = (1/\hat{\psi}) \Gamma(\hat{\psi} + 1)$. The equations used to find the ZSE parameter simplify to

$$
\frac{k\psi}{\lambda_i} \left[ 1 - \left(\frac{\lambda_i}{\phi_i}\right)^\psi \Gamma(\frac{\psi}{\hat{\psi}} + 1) \right] = 0,
$$

which lead to the solutions $\phi_i = \lambda_i \Gamma(\psi/\hat{\psi} + 1)$, $i = 1, \ldots, n$.

### A.3 Integrated likelihood in the Weibull model: Random censoring

First, using the conditional expectation in (23) it can be shown that

$$
E\{\Delta_{ij}; \hat{\psi}, \phi_i, \nu\} = E_{C_{ij}} \left\{ E_{\Delta_{ij}|C_i=c_{ij}} \{ \Delta_{ij}; \nu \} \right\}
$$

$$
= 1 - \int_0^\infty S_t(c; \hat{\psi}, \phi_i) g(c; \nu) dc
$$

$$
= 1 - \int_0^\infty \nu e^{-\left(\phi_i, c\right)^\psi - \nu c} dc,
$$

and using the conditional expectation in (24) it can be shown that

$$
E\{T_{ij}^\psi; \hat{\psi}, \phi_i, \nu\} = E_{C_{ij}} \left\{ E_{T_{ij}|C_i=c_{ij}} \{ T_{ij}^\psi; \nu \} \right\}
$$

$$
= \int_0^\infty \nu f_{T_{ij}}(t; \hat{\psi}, \phi_i, \nu) dt
$$

$$
= \int_0^\infty \nu \left( t^{\psi-1} \hat{\psi}^\psi \right) e^{-\left(\phi_i, t\right)^\psi - \nu t} dt,
$$

where $f_{T_{ij}}(t; \psi, \lambda_i, \nu) = p_i(t; \hat{\psi}, \lambda_i) G_i(t; \nu) + q_i(t; \nu) S_i(t; \psi, \lambda_i)$. Therefore, it is sufficient to substitute these expected values within equation (15) by considering the maximum likelihood estimate $\hat{\nu}$ as a plug-in estimate for $\nu$. It leads to the final form of the zero-score equations

$$
k \frac{\psi}{\lambda_i} E\{\Delta_{ij}; \hat{\psi}, \phi_i, \hat{\nu}\} - k \psi \lambda_i^{-1} E\{T_{ij}^\psi; \hat{\psi}, \phi_i, \hat{\nu}\} = 0.
$$

Solutions for $\phi$ are not in closed form. However, in order to compute the integrated likelihood function for $\psi$, the original nuisance parameter $\lambda_i$ can be easily written as a function of the zero-score $\phi_i$ as follows

$$
\lambda_i(\phi_i) = \left[ \frac{E\{\Delta_{ij}; \hat{\psi}, \phi_i, \hat{\nu}\}}{E\{T_{ij}^\psi; \hat{\psi}, \phi_i, \hat{\nu}\}} \right]^{1/\psi}.
$$
A.4 Zero-score expectation parameter for the accelerated failure time regression model

In this setting, the strata have different sizes and the parameterization depends also on covariates. Therefore from equations (15) and (26), the ZSE equations for finding the $\phi_{ij}$ reduce to

$$E\{\ell_{n_j}(\psi, \eta_j); \hat{\psi}, \phi_{ij}, \hat{\nu}\} = \frac{\psi_1}{n_j} E\{\Delta_{ij}; \hat{\psi}, \phi_{ij}, \hat{\nu}\} - \psi_1 \eta_j^{\psi_1 - 1} E\{T_{ij}^{\nu}; \hat{\psi}, \phi_{ij}, \hat{\nu}\}. \quad (28)$$

The following relation holds

$$E\{\ell_{n_j}(\psi, \eta_j); \hat{\psi}, \omega_i, \hat{\nu}\} = \sum_j \left(\frac{\partial n_j}{\partial \alpha_i}\right) E\{\ell_{n_j}(\psi, \eta_j); \hat{\psi}, \phi_{ij}, \hat{\nu}\} = - \sum_j n_j E\{\ell_{n_j}(\psi, \eta_j); \hat{\psi}, \phi_{ij}, \hat{\nu}\},$$

where $E\{\ell_{n_j}(\psi, \eta_j); \hat{\psi}, \phi_{ij}, \hat{\nu}\}$ is given in (28).

Consequently, substituting the new parameterization for $\eta_{ij}$ and $\phi_{ij}$ (equation (19)) in the latter expression and setting it equal to zero, yields

$$\alpha_i(\omega_i) = - \frac{1}{\psi_1} \log \left[ \frac{\sum_j E\{\Delta_{ij}; x_{ij}, \hat{\psi}, \omega_i, \hat{\nu}\}}{\sum_j E\{T_{ij}^{\nu}; x_{ij}, \hat{\psi}, \omega_i, \hat{\nu}\}} \right]. \quad (29)$$